# Fitting ACT-R Models with Trial-by-Trial Maximum Likelihood

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# **Fitting models**

- We all do. That's part for the job!
- But what do we **fit for**?
- In most cases, we **minimize** RMSE or  $R^2$
- Suggestion: We should use Maximum Likelihood (MLE)
- In linear models, minimizing RMSE and maximizing log-likelihood are the same
  - $\circ$  ... and they both maximize  $R^2$
- When we use **non-linear** models, however, things are different
- And ACT-R has several non-linear equations

# What is MLE?

Find parameters  $\boldsymbol{\theta}$  of a model that maximize likelihood  $\boldsymbol{\pounds}$ 

$$\mathcal{L}(m, \theta \mid x) = P(x \mid m, \theta)$$
model parameters data

In practice, you use **log**-likelihood, because probs become vanishingly small when there are series of products

$$\log \mathcal{L}(m, \theta \mid x) = \log P(x \mid m, \theta)$$

# Why would you use log-likelihood?

Intuitively, that is what you are trying to do: Finding the most probable model. But, also:

- It allows **comparison** across models with different complexity
  - BIC and AIC are expressed as a function of log likelihood:

 $BIC = k \log(n) - 2 \log \mathcal{L} \qquad AIC = 2k - 2 \log \mathcal{L}$ 

- It allows fitting to **individuals** as well as **group** data
  - Group-level log likelihoods are the sum of individual log likelihoods!

### How to do it – easy way

- Set your values for m and  $\theta$
- Run many simulations
- Calculate mean and standard deviation
- Compare to subject data point **x**



Participant data

# Limits

ACT-R models often takes a long time to run

Necessary to run model many times to get stable data

Aggregated data often contains very few data points

# **Trial by trial**

# **Trial by trial likelihood**

$$\mathcal{L}(m, \theta \mid \mathbf{x}) = P(\mathbf{x} \mid m, \theta); \quad \mathbf{x} = \{x_1, x_2, \dots, x_N\}$$

$$P(\mathbf{x} \mid m, \theta) = P(x_1 \mid m, \theta) \cdot P(x_2 \mid m, \theta, x_1) \cdot \dots \cdot P(x_N \mid m, \theta, x_1, x_2 \dots x_N)$$
ACT-R is a Markov model, and every choice is determined only by the current state.

So, if we force the model to follow the choices:

$$P(\mathbf{x}|m, \theta) = P(x_1|m, \theta) \cdot P(x_2|m, \theta) \cdot \dots \cdot P(x_N|m, \theta)$$
$$\log \mathcal{L} = \sum_i \log P(x_i|m, \theta)$$

This is just model tracing! (Koediger & Anderson, 1993)

# Advantages of trial by trial data

- You get more data points for every individual
- Aggregated data can be deceiving:



# **Example: Incentive Processing Task**





- N = 199 participants
- 2 runs for each participant
- 4 blocks per run (2 Win, 2 Loss)
- 8 choices per block
- 64 trials total

### Two ways to approach the task

#### **Procedural Memory**



#### **Declarative Memory**



 $U_{t}(p) = U_{t1}(p) + a[R - U_{t1}(p)]$ 

 $A_t(c) = \sum_j (t - t_j)^{-d}$ 

 $P(more) = e^{U(more)/T} / e^{U(more)/T} + e^{U(less)/T}$ 

$$P(more) = e^{A(more)/s} / \sum_{chunk} e^{A(chunk)}$$

# **Model-Based Group Assignment**

Implemented equations in Python

For every participant:

- Use Powell's method to maximize Declarative log-likelihood across parameters (θ)
- Repeat for Procedural
- Assign participant to the model with greater likelihood

Total runtime: ~ 20 mins!





https://github.com/UWCCDL/ProcVsDecl/

Yang et al, BioArXiv

### **Participant assignments**

Distribution of Model Log-Likelihood Differences



# How Reliable are our Models?

- Generated 20,000 simulated runs for each model
  - with random initial params
- Applied trial-by trial MLE to recover model



### **Differences btw Declarative and Procedural groups**



Behavioral Differences Between Groups

# **Differences btw Declarative and Procedural groups**

Procedural - Declarative Groups Durings Task

Medial Right





Lateral Right

Medial Left

Lateral Left





# **Mixing different measures**

# Better memory after errors

#### **Elaborative Hypothesis**



#### **Mediator Hypothesis**



#### Mediator predicts longer RTs!

Leonard et al., 2022 CogSci

### **Mixing different measures**

$$A_t(c) = \sum_i (t - t_i)^{-d} + s$$
$$P(c) = e^{A(c)/s} / \sum_i e^{A(i)/s}$$

But ACT-R also makes **predictions about RTs**:

$$rt = t_0 + F e^{A(c)}$$
$$P(\mathbf{x}_i | m, \theta) = P(c_i | m, \theta) + P(rt_i | m, \theta)$$



### **Mediator vs Elaborative**



Evidence for Mediator = sum of individual  $\Delta LL = 1,728$ . Mediator is  $e^{1,728}$  more likely

# **Accurate Parameter Recovery**

### Accurate parameter recovery

In my lab, we make a big deal about understanding individuals using parameters

But to make sense, these parameters need to be accurate

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#### Parameter Recovery Results

### PSS Task (Frank et al., 2004)



**ChooseA** and **AvoidB** are proxies for D1/D2 dopamine receptors

# **Poor reliability**



**Test-Retest Correlation** 

Xu & Stocco, 2021, Comp. Brain Behav.

### Including D1/D2 parameters in ACT-R model



### Parameters have greater reliability!



# **Tracking memory decline**

Long-running study to track memory decay in 47 elderly individuals

Really, **a** param in Pavlik & Anderson ("Speed of forgetting", **SOF**)

Weekly tests over one year

Mean correlation r = 0.72



#### SoF Correlations Across Topics

Hake et al, 2023, *CogSci* **\*** Applied Modeling Award

# **Differences in memory predict cognitive impairment**



Adjusted  $r^2 = 0.38$ 

# Summary

Reasons to use Maximum Likelihood (especially trial-by-trial)

- Clear interpretation
- Comparisons between models of different complexity
- Can mix multiple measures
- Reliable individual differences

### **Even shorter summary**



### Super special thanks to...









