



AFRL

Challenges and Strategies for Extending ACT-R Visual Perception

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COGNITION AND MODELS BRANCH | JULY 19TH 2023



Motivation – We Could do More with ACT-R

General Areas

- Human factors/usability research
- Realistic tasks and stimuli (visual and auditory)
 - e.g., air tanker refueling/search and rescue at night
- Phenomena of interest
 - Cognitive load, executive control during multitasking, attention control, and fatigue/vigilance

Specific Efforts:

- Detecting fatigue and its effects on visual search
- Measuring cognitive load in radar monitoring
- Target identification with night vision goggles



Why Use ACT-R?

- Cognitively plausible and scientifically validated
- Interactions between cognitive processes
 - Fatigue from sleep/time on task
 - Memory
 - Attention
 - Executive control
- Predict and explain behavior
- Human representation in large simulations



Challenges and Open Questions

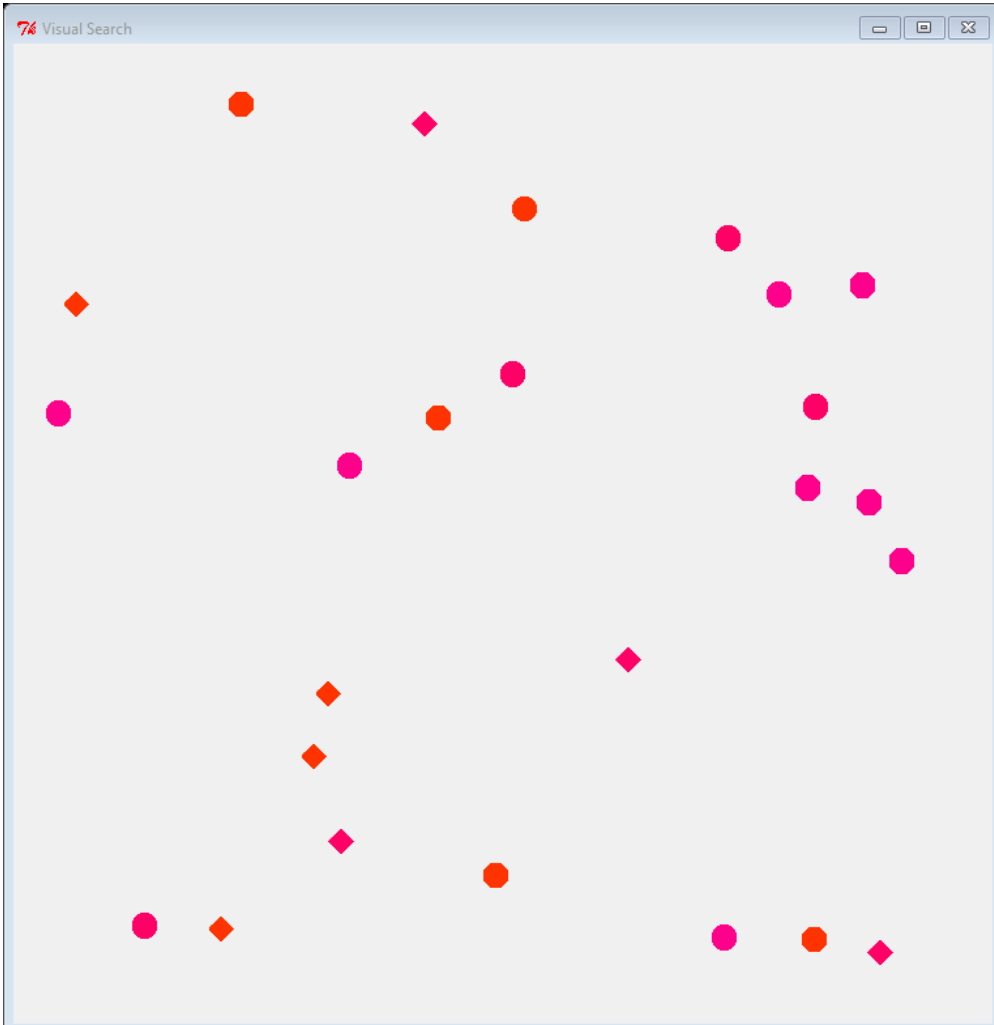
- Challenges
 - Visual/auditory perception limitations
 - Fatigue module scaling/updating
 - Scaling-up closer to real-world tasks
- Technical Questions
 - Bottom Up - Visual attention?
 - Fatigue mechanisms
 - Low-level perception – Acuity and contrast?
- Theoretical Questions
 - Fatigue – perceptual or executive control?
 - Fovea and peripheral?
 - Perceptual vs Productions



Top-down and Bottom-up Visual Processing

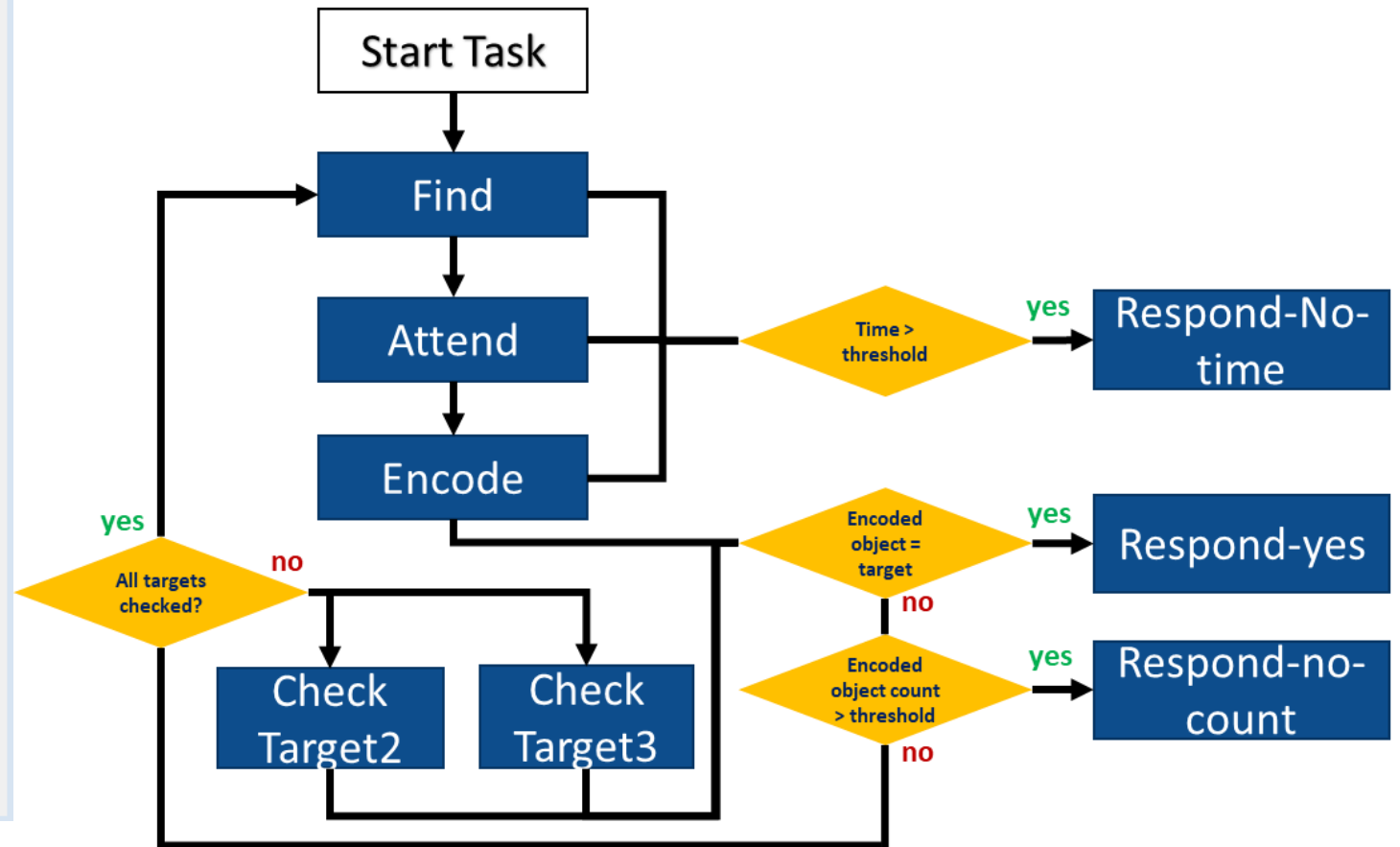


Visual Search with Fatigue – Experiment

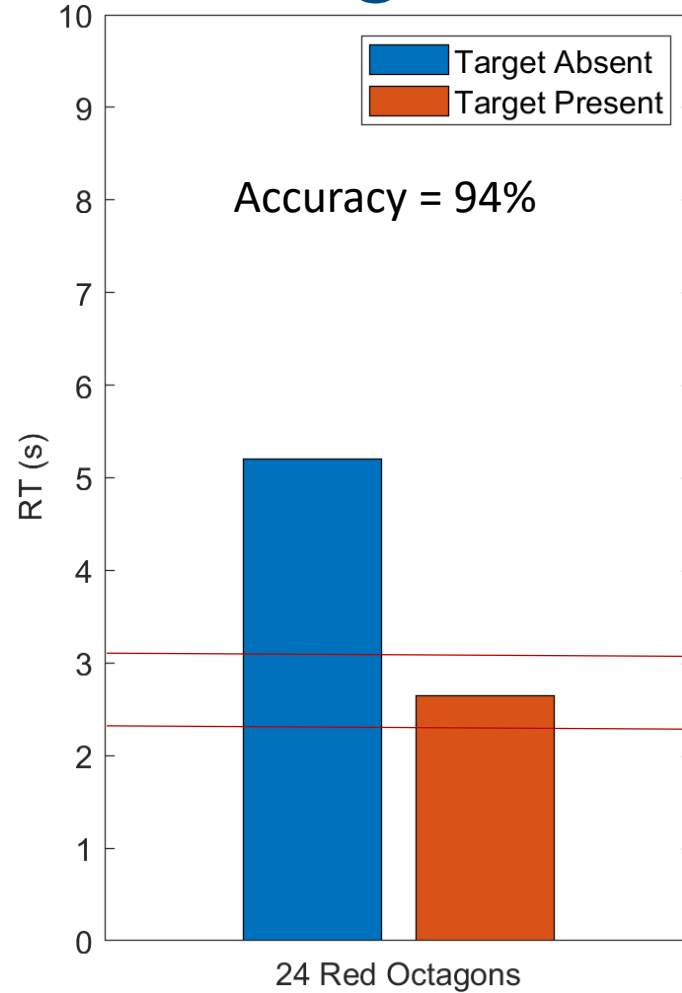
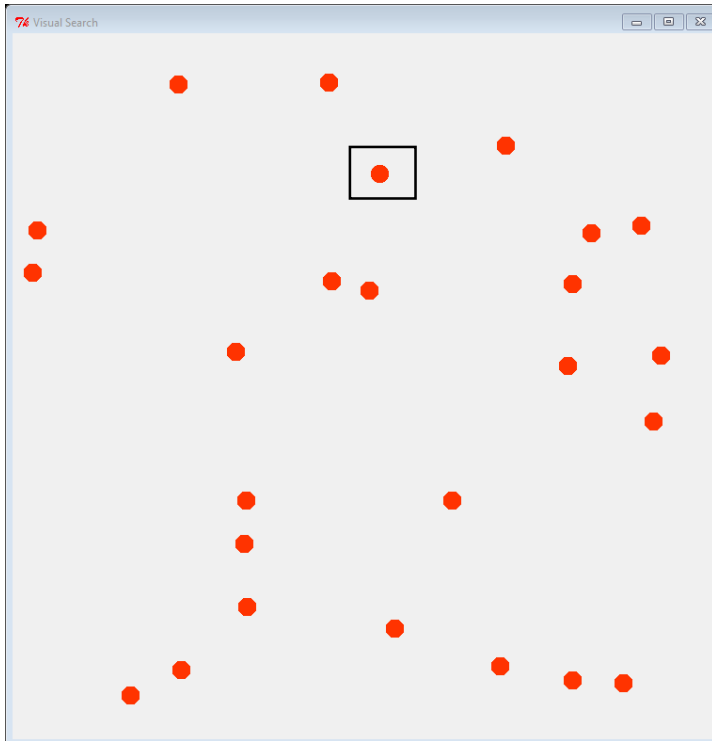
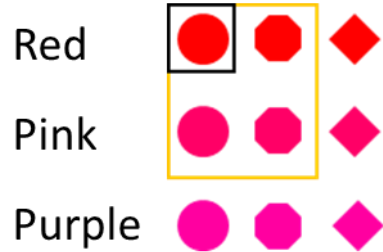


Shapes: ● ● ◆
Colors: red - pink - purple

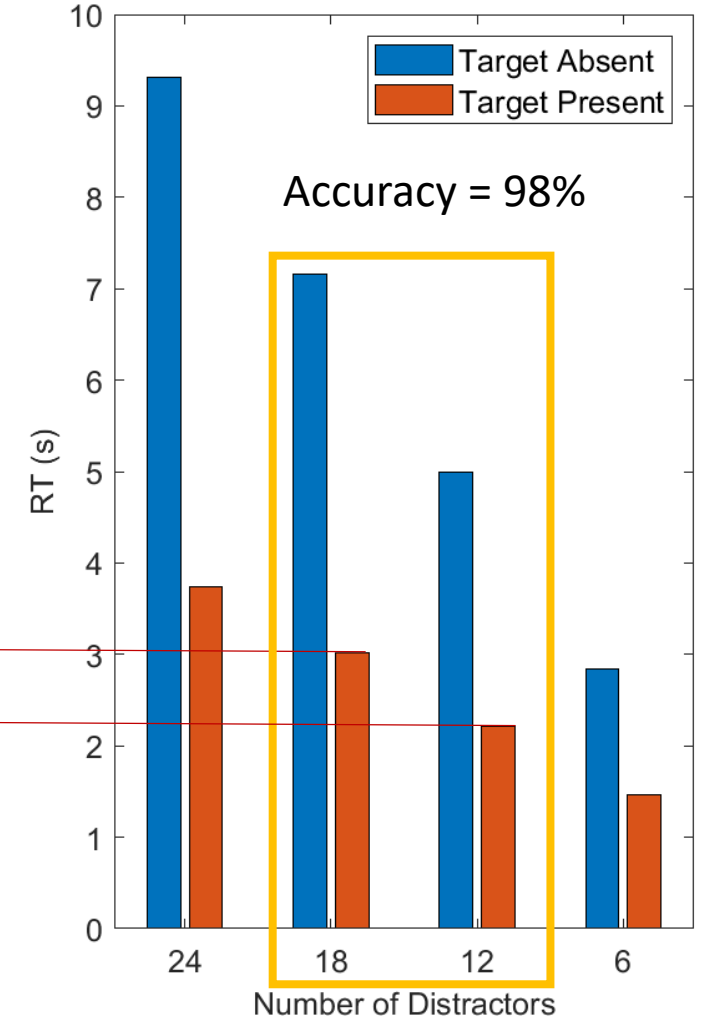
Amount of targets (1 or 3)
Target-present trials (10% or 50%)



Visual Search with Fatigue – Model

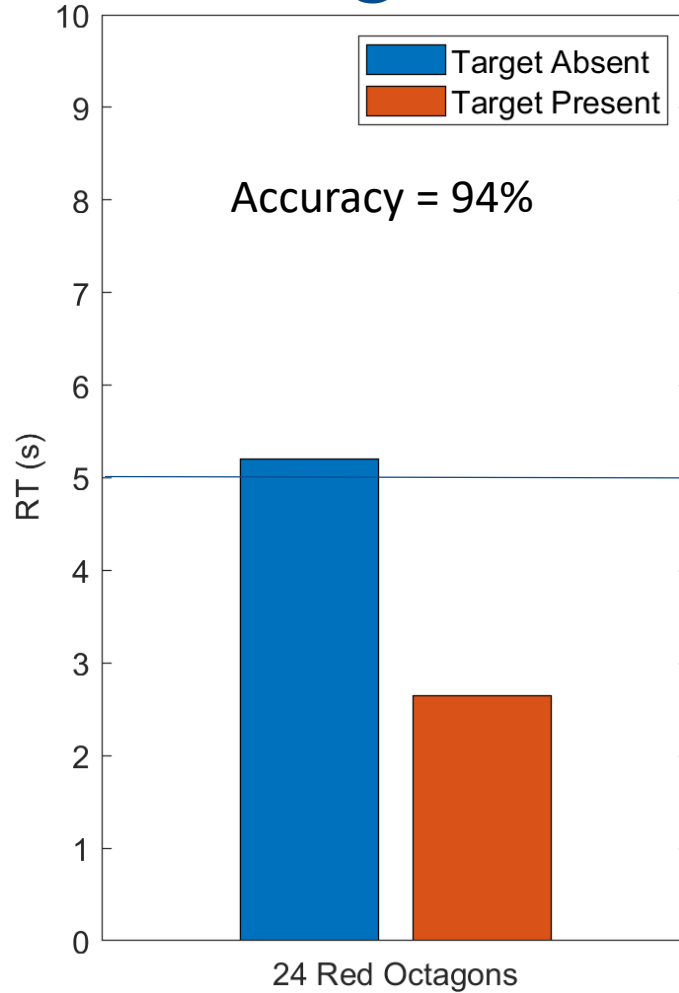
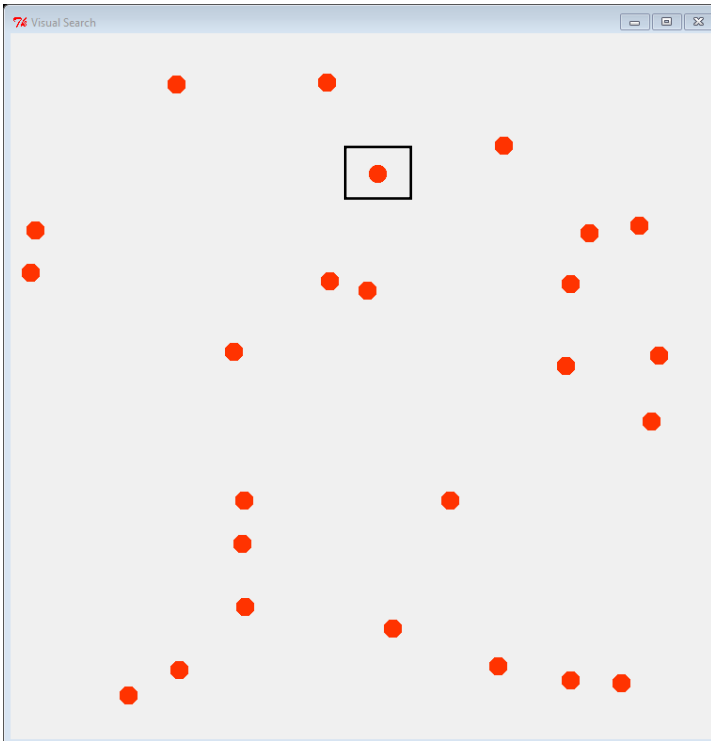
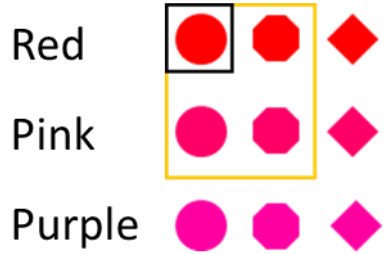


Glavan et al. (2020)

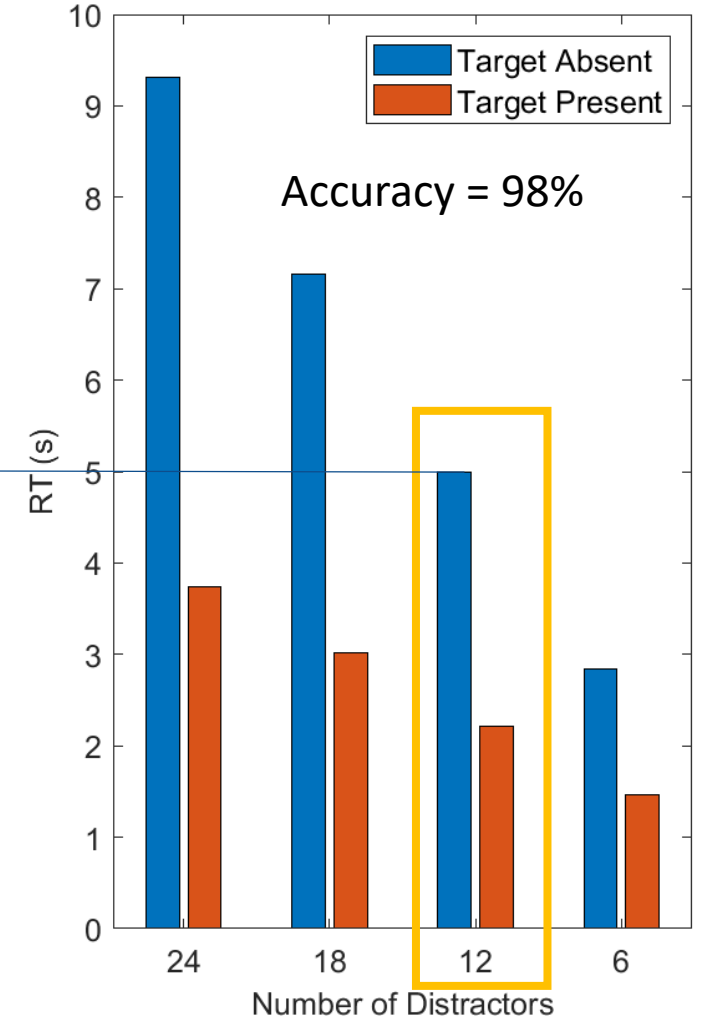


Model

Visual Search with Fatigue – Model



Glavan et al. (2020)



Model

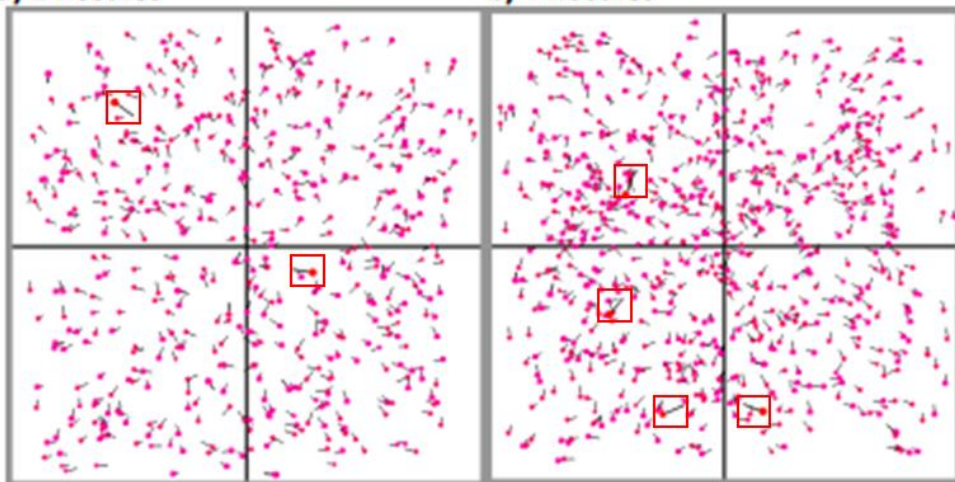
Radar Detection – MOT-EW Task (Fox et al., 2023)

Quad alarms (MOT task) EW alarm (EW task)



a) 2 hostiles

b) 4 hostiles

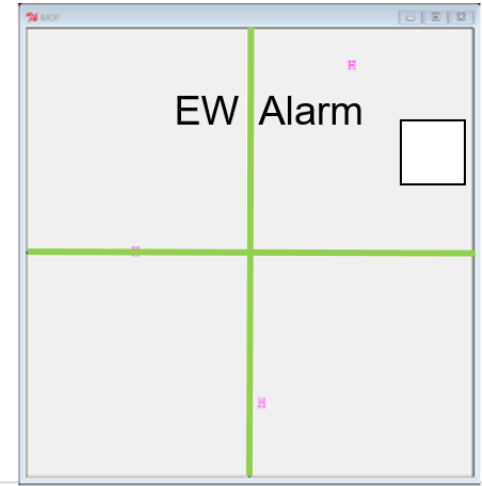


d) 2 hostiles, 498 friendlies

e) 4 hostiles, 696 friendlies



a) 2 hostiles



b) 4 hostiles



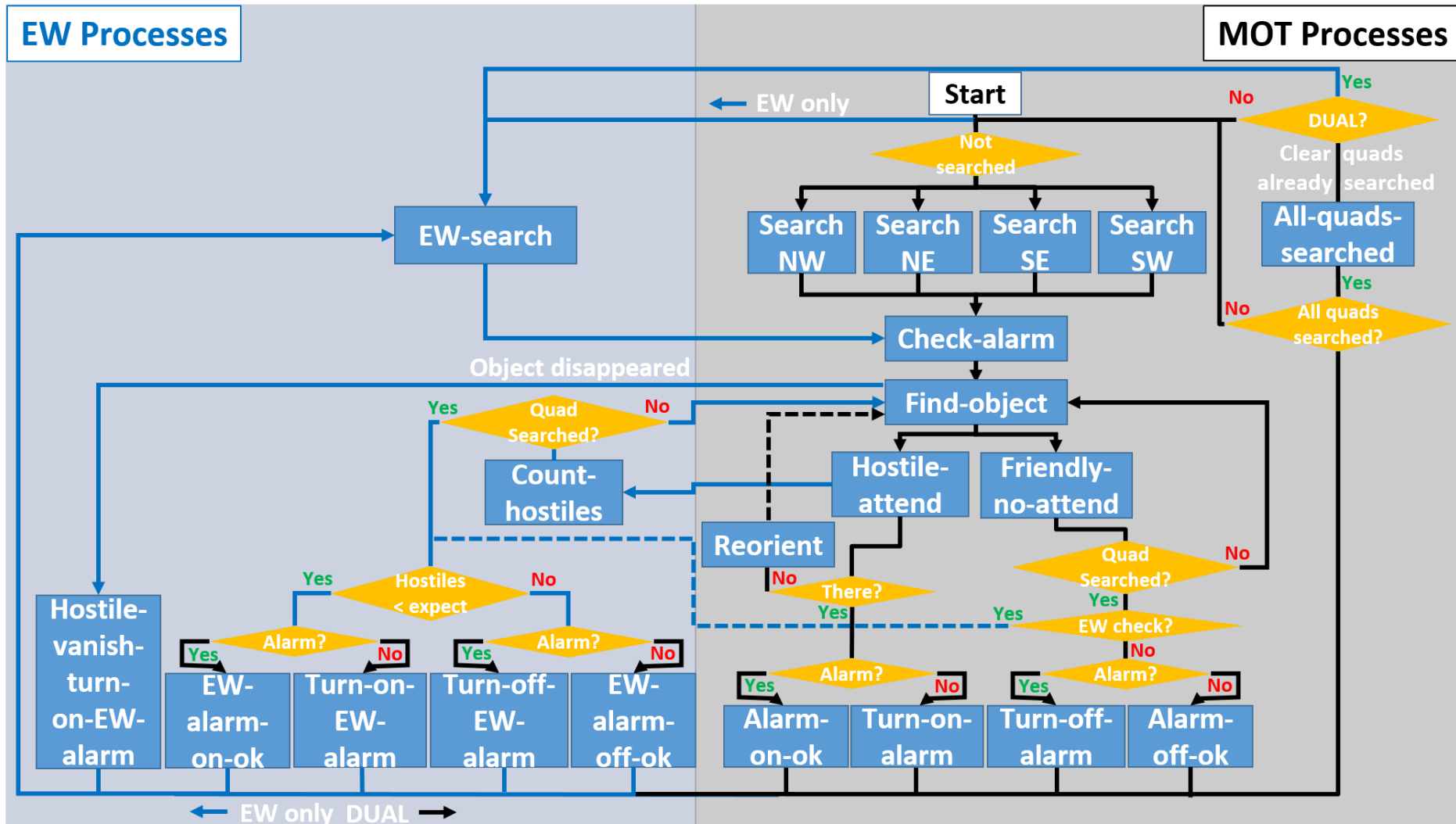
d) 2 hostiles, 4 friendlies



e) 4 hostiles, 6 friendlies



Radar Detection – MOT-EW Model (Hough et al., 2023)

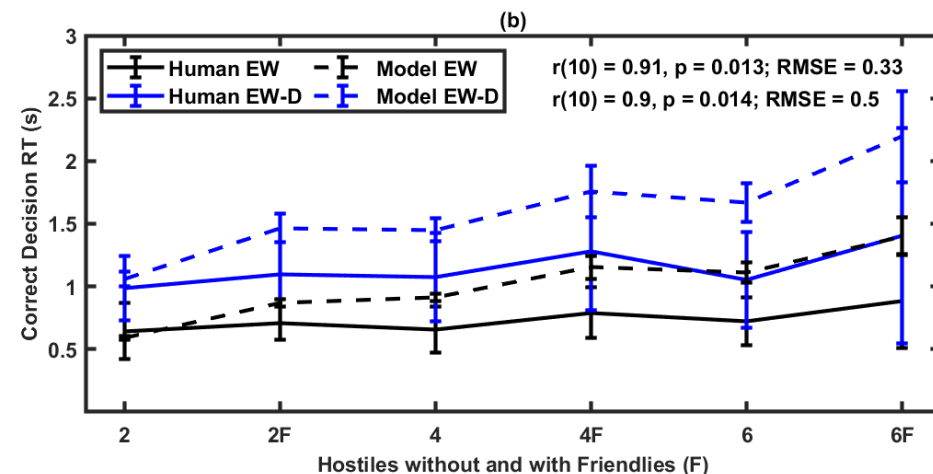
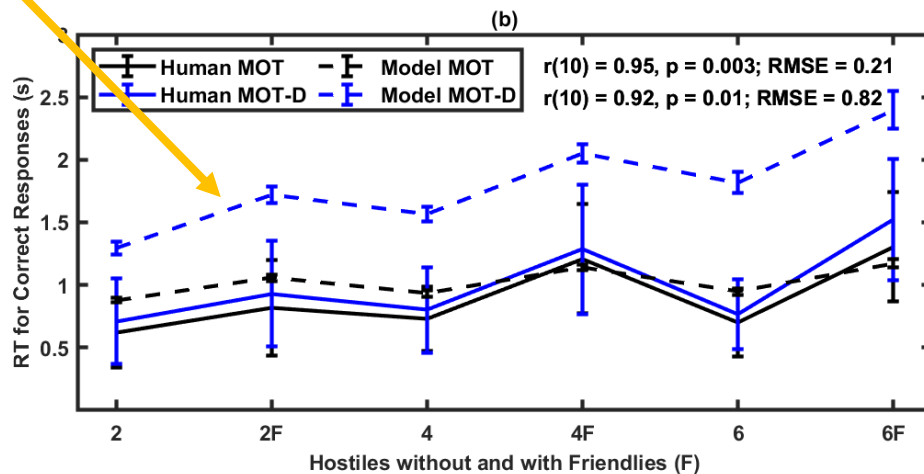
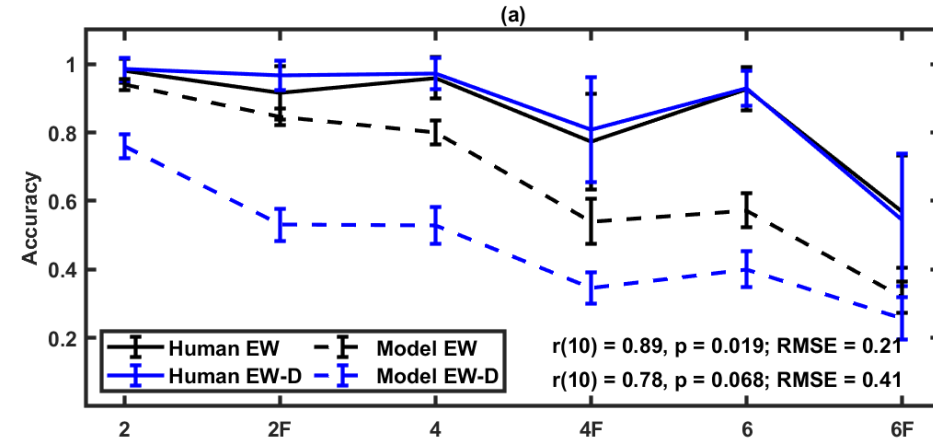
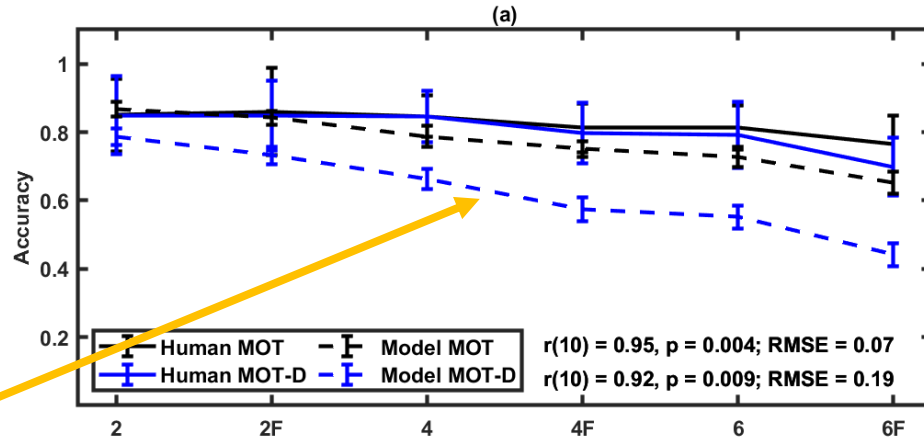




Radar Detection – MOT-EW Model (Hough et al., 2023)

MOT

EW





How to Extend ACT-R Visual Attention?

Challenges

- Selective visual attention
- Overloading the visicon
- Finsts – number and span

Potential and Previous Methods

- Perception span and buffer stuffing (Swan et al., 2023)
- Preattentive and attentive visual module (PAAV) (Nyamsuren & Taatgen, 2013)
- PAAV inspired Java implementation (Fisher et al., 2022)
- “Light” PAAV in Julia (Fisher et al., 2023)
- ACT-R and PAAV outside architecture (Jokinen et al., 2020)
- JSegMan (Tehranchi & Ritter, 2018)
- EPIC (Kieras, 2019)

Considerations

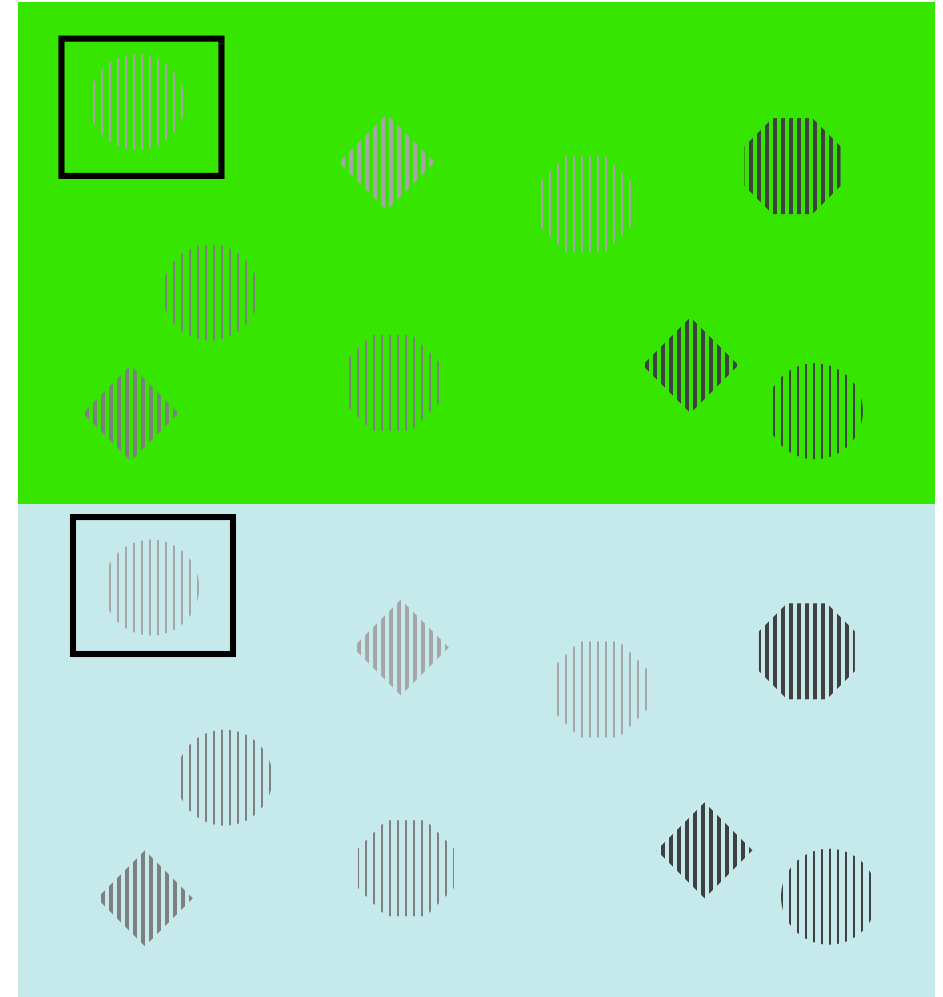
- **ACT-R module(s)**
- Computational costs
- Task independence and scaling



Low-level Visual Perception (Pre-processing)

Visual Search and Eye-strain Fatigue with NVGs

- Modified visual search task
 - Difficulty manipulations
 - Acuity, contrast, line orientation instead of color
- Goals:
 - Experiment and modeling
 - Perceptual/performance differences
 - Eye-strain related fatigue/impacts
 - Predict/explain/simulate behavior
- Modeling Needs
 - Perception of gradients
 - Acuity and contrast effects



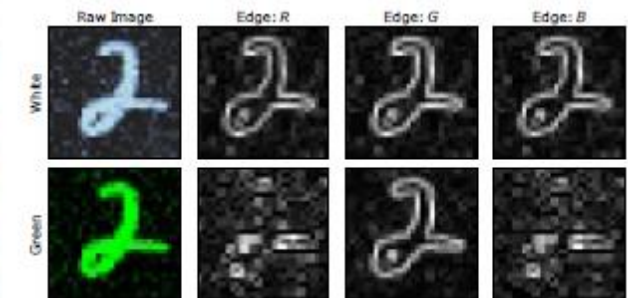
Visual Search and Eye-strain Fatigue with NVGs

- Leabra (O'Reilly, 2006; O'Reilly et al., 2017)
- NVG test cases using Julia (Curley, 2022)
 - Prefer white over green
 - Weak opponent processes?
 - Stimuli with MNIST digits simulating NVGs
- Low-level perceptual features for ACT-R?



- Preliminary results

- Model has more trouble with green edge detection
- Opponent processes





How to Extend ACT-R Low-level Visual Perception?

Challenges

- Bottom-up attention not sufficient
 - Visicon or iconic visual memory
- Computation costs
- Integration with ACT-R

Potential and Previous Methods

- Integration with Leabra or other architectures
- Adding additional features to visicon

Considerations

- Low computational/time costs
- Selective decomposition
- Scaling and generalization
- **ACT-R module?**



Discussion



Why, What, and How?

- Why?
 - Human factors/usability research
 - Realistic tasks and stimuli (visual and auditory)
 - Cognitive load, multitasking, attention control, and fatigue/vigilance
- What?
 - Bottom-up attention
 - Low-level perception
 - Generalizable module(s) maintained with architecture
- How?
 - Leveraging previous work
 - Open discussions and collaboration
 - Post-docs, proposals, grants...



THANK YOU!

Christopher Myers
Christopher Stevens
Taylor Curley

QUESTIONS?

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References

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Visual Search with Fatigue – Literature

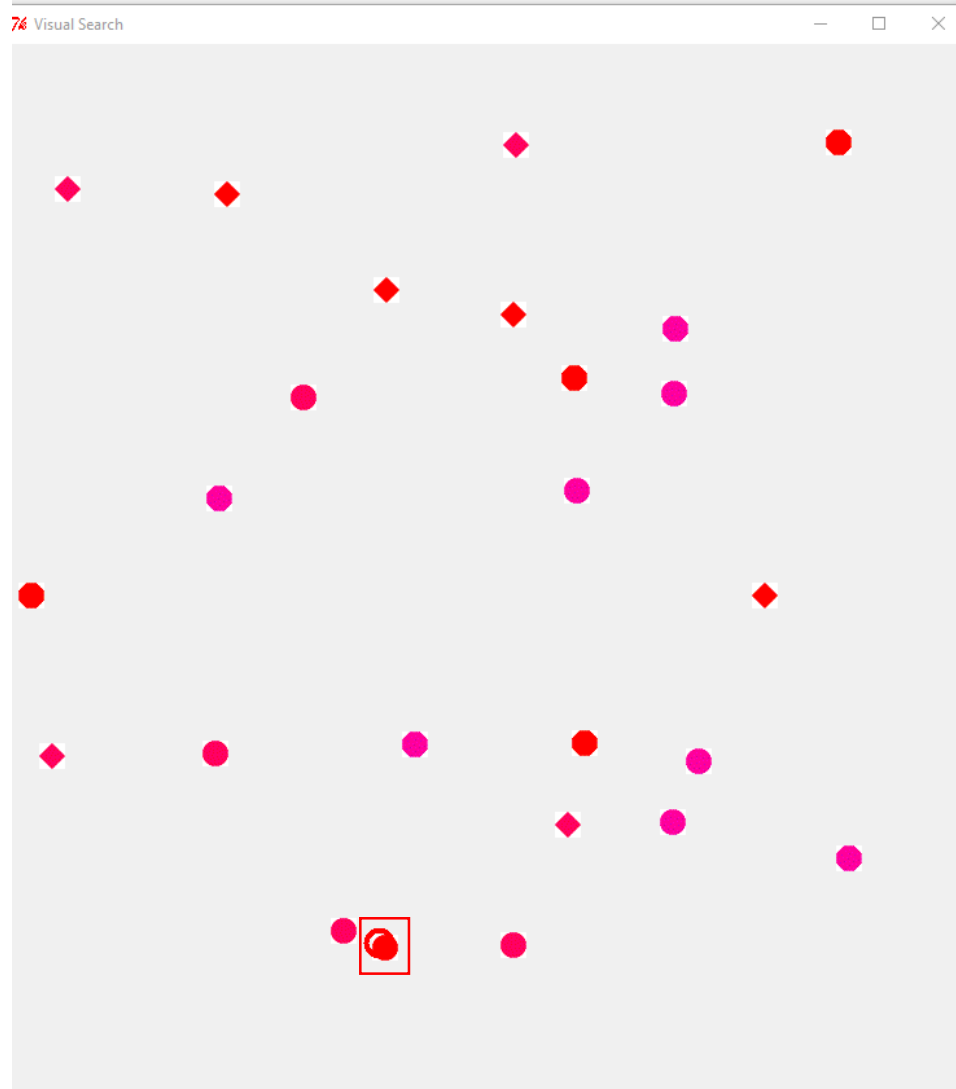
Time-on-task fatigue/vigilance decrement

- Performance declines over time (Grier et al., 2003; Parasuraman, 1979; Helton et al., 2007)
- Resource depletes → workload/TOT (Helton & Russell, 2013; Shaw et al., 2013; Warm et al., 2008)
- Lack cog/physio understanding – TOT fatigue in complex tasks

Visual search




- TOT → more missed targets (Horowitz et al., 2003; Wolfe et al., 2007)
- Increased difficulty - # distractors, similarity, # targets, & target prevalence (Treisman & Gelade, 1980; Treisman & Paterson, 1984; Wolfe et al., 2005, 2007; Wolfe, 2012)
- Lack - cog models & understanding of fatigue in visual search




Visual Search with Fatigue – Experiment






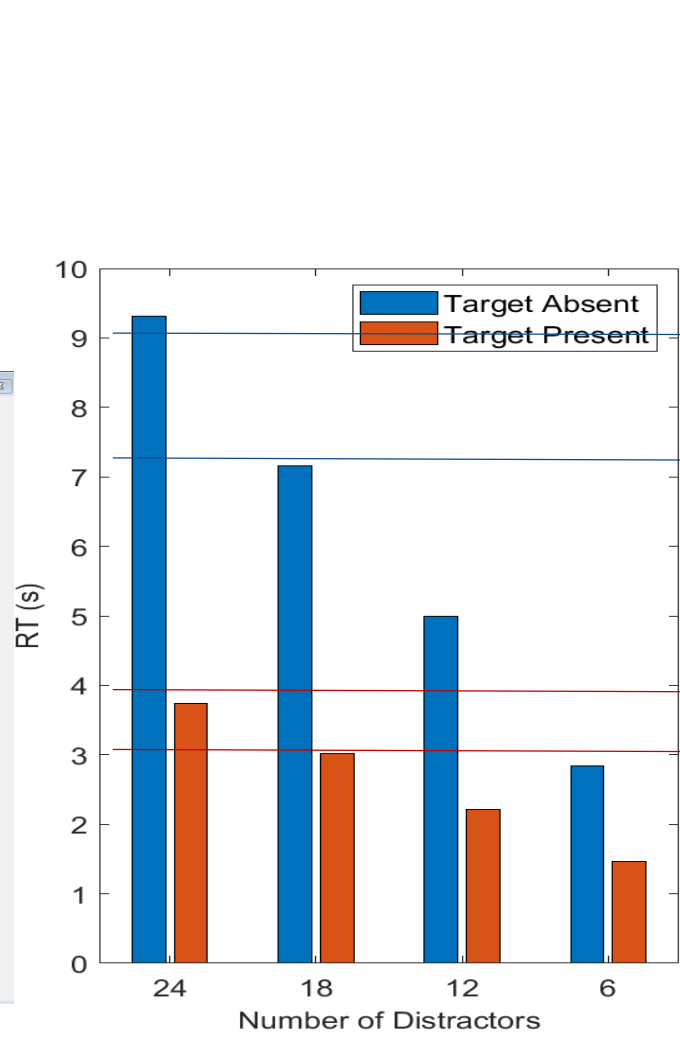
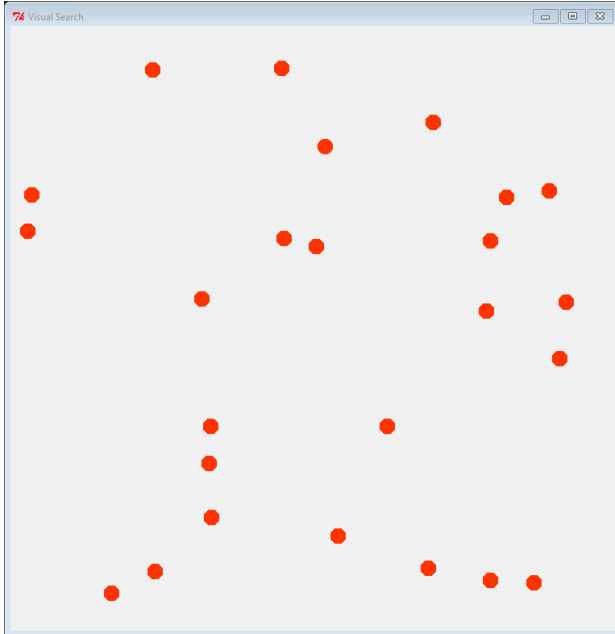
- Stimuli (Glavan et al., 2020)
 - Distractors (24)
 - Shapes: ● ○ ◆
 - Colors: red - pink - purple
- Design
 - 500 trials
 - Two IVs – 4 conditions
 - Target-present trials (10% or 50%)
 - Amount of targets (1 or 3)
 - Measures
 - Accuracy, RT, eye tracking, and EEG

Visual Search with Fatigue – Model

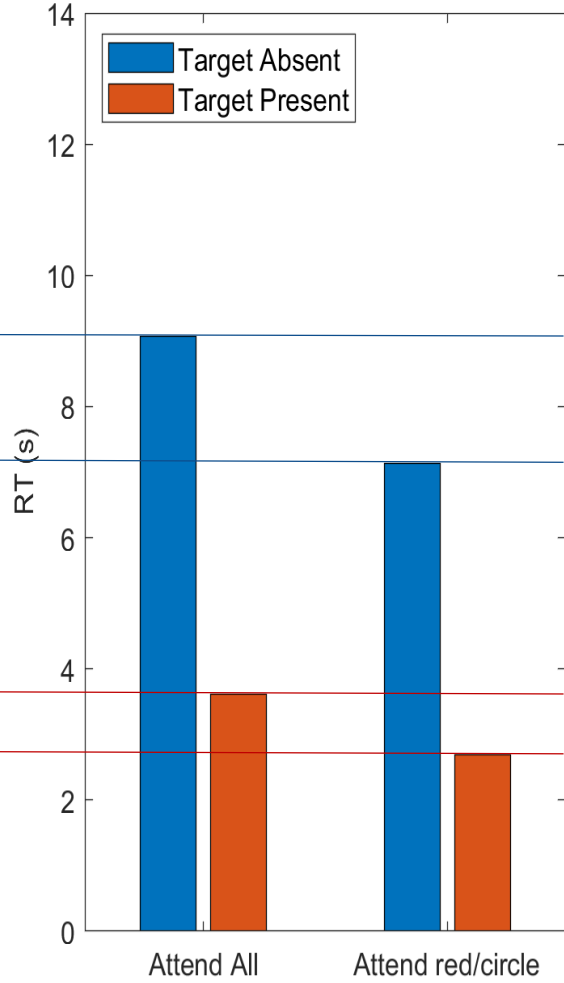
Red   

Pink   




Purple   









Red octagons

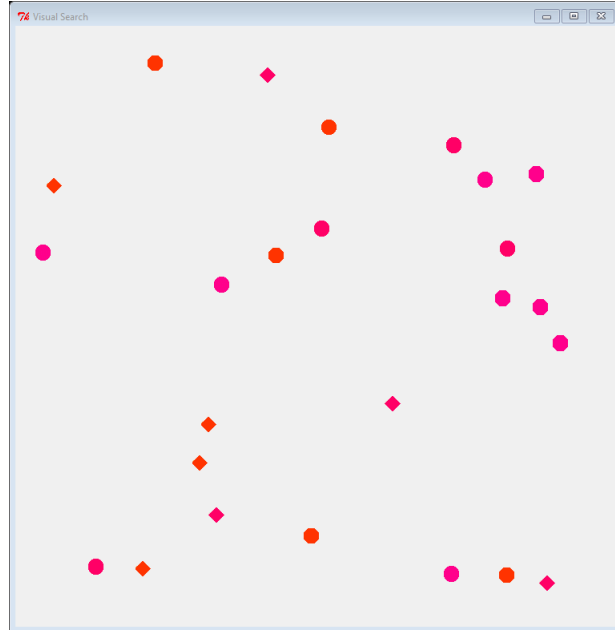


Varied distractors



Red   

Pink   

Purple   



Radar Detection – MOT-EW Task (Fox et al., 2023)

- MOT Task (Fox et al., 2023)
 - Hostiles (targets) 
 - Friendlies (distractors) 
 - MOT- Hostiles and quad alarms
 - EW – Attacks and EW alarm +
 - Conditions – single/dual and # objects
- MOT Model
 - Need human-like visual search

