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Modeling well-learned *iDiosp*ncRatiC non-optimal micro strategies

Set Up

Memory Game

- DEMO available on Google Play Store;
- '4 Button Expert'

3 highly trained individuals

- 19-24 y/o females
- Learning the game over months

Predictive ACT-R Model

Based on SGOMS

Related studies

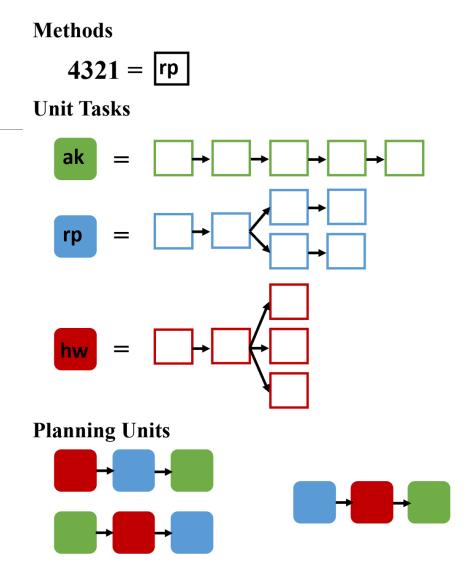
- Gray and Boehm-Davis (2000)
- Shiffrin and Cousineau (2004)

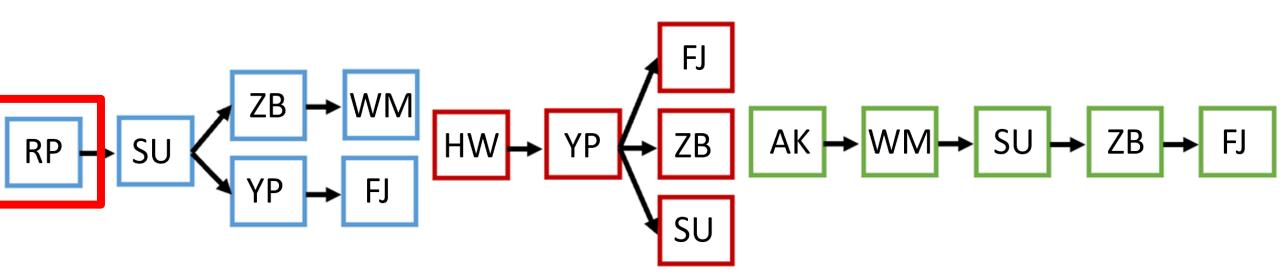
The Game

The Game was designed following the SGOMS hierarchy.

Participants learned each level fully before moving to the next.

For our study we developed the Game as a mobile app. The following slides demonstrate how the game works.





 Score:
 Collect Data

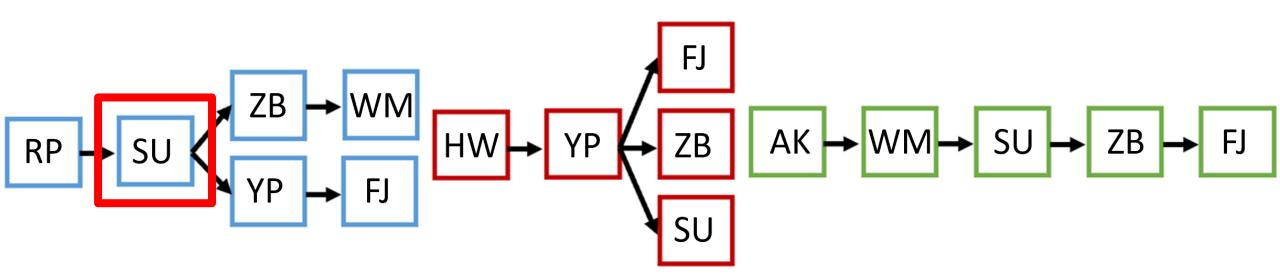
 rp

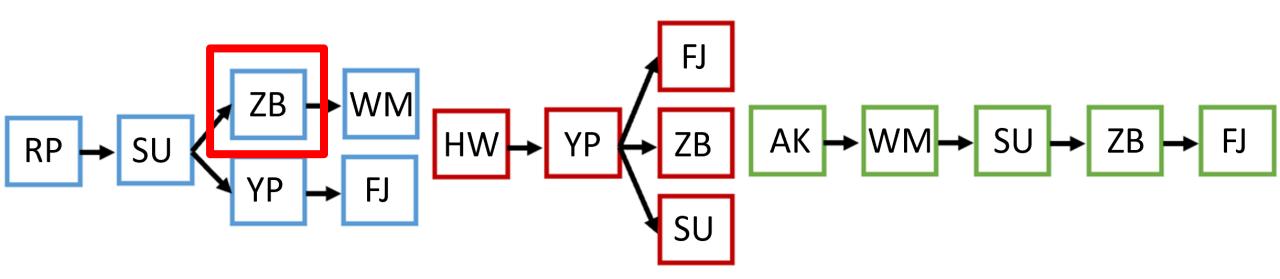
 1
 2

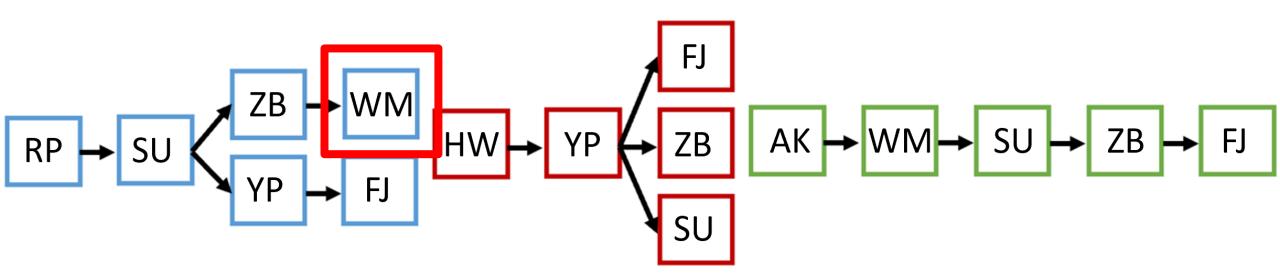
 3
 4

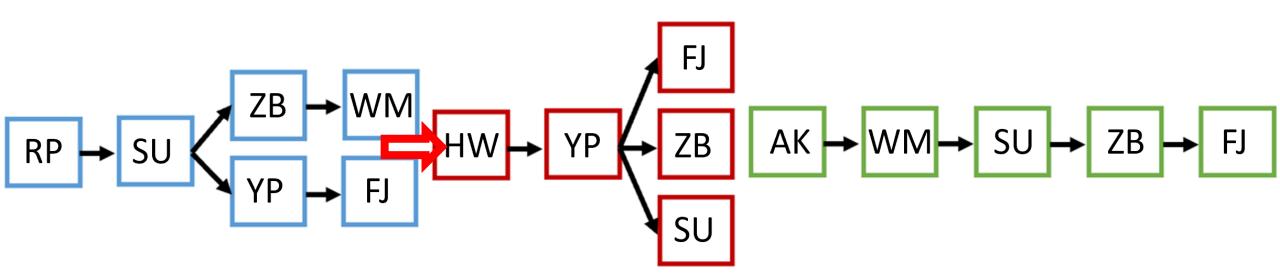
 Start Game

 End Game

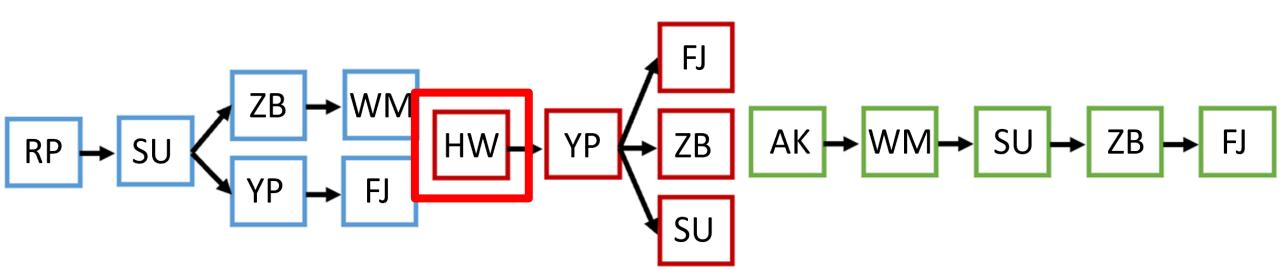








Score: 20 Collect Data Correct WW 1 2 3 4 Start Game End Game



Score: 26 Collect Data
Correct

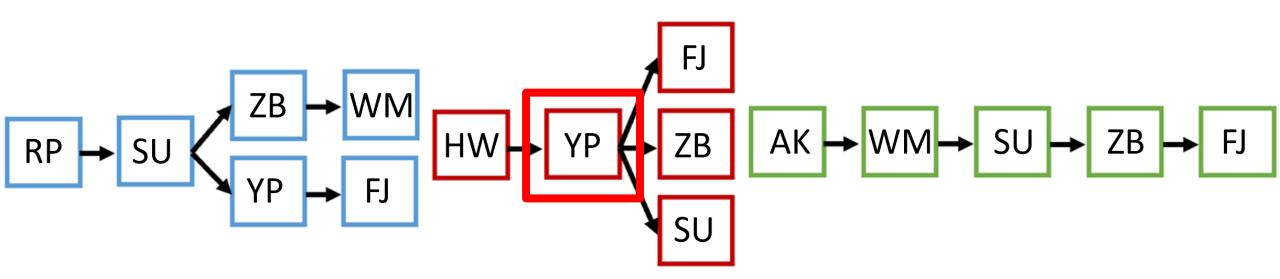
 hw

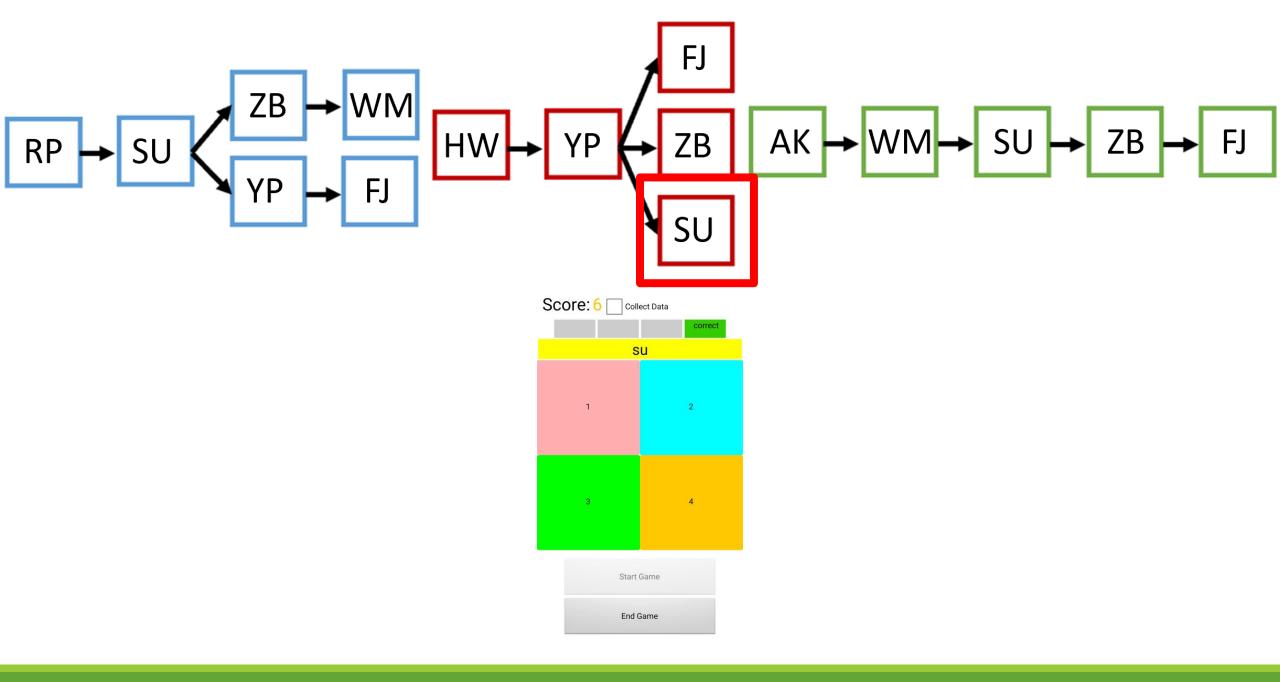
 1
 2

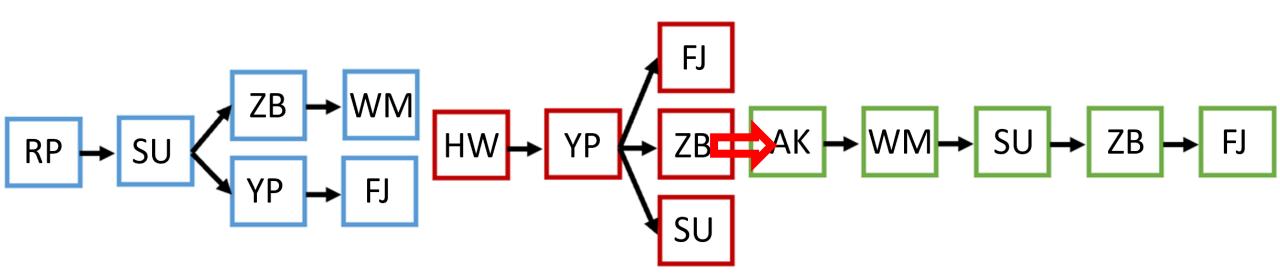
 3
 4

 Start Game

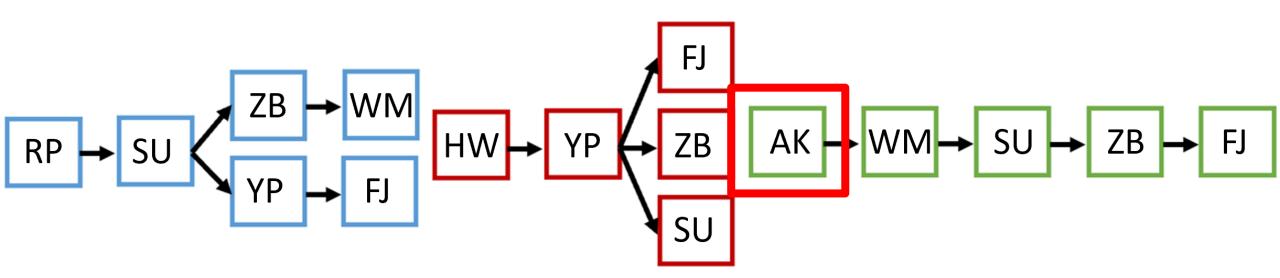
 End Game

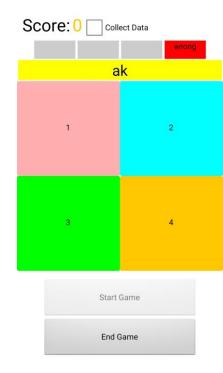


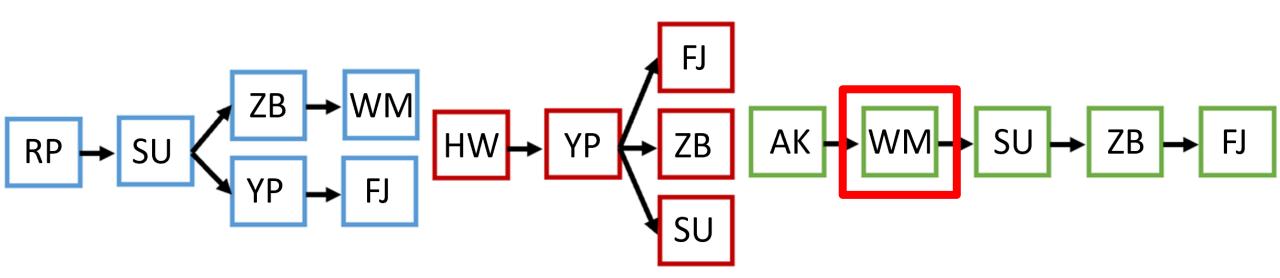


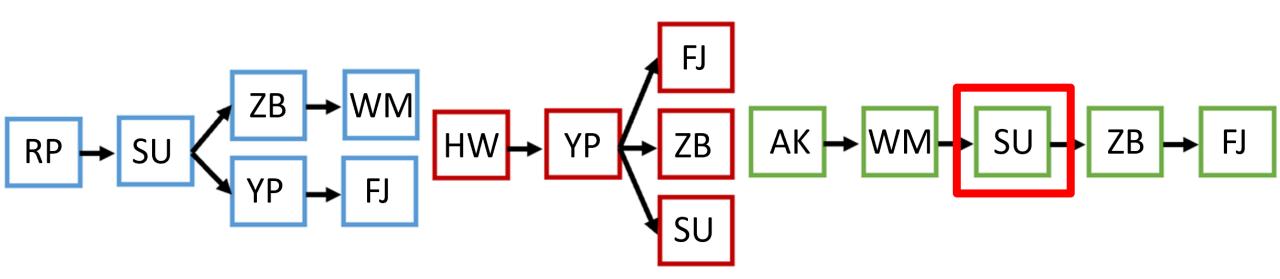


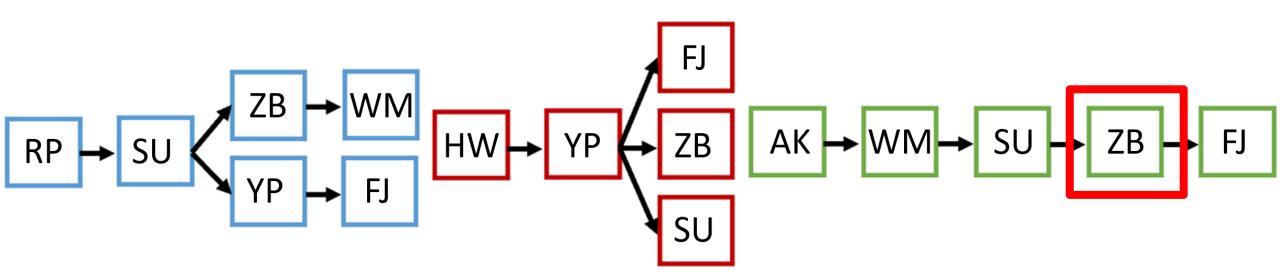
Score: 6 Collect Data
Correct
SU



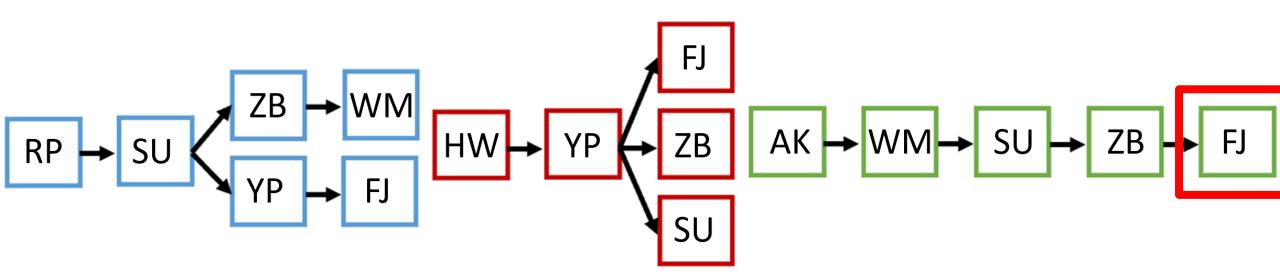






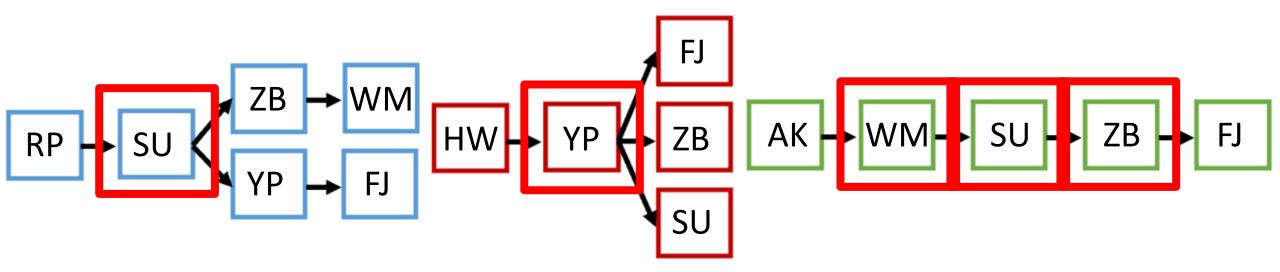


Score: Collect Data Vrong
Collect Data
Vrong
Collect Data
Collect Dat

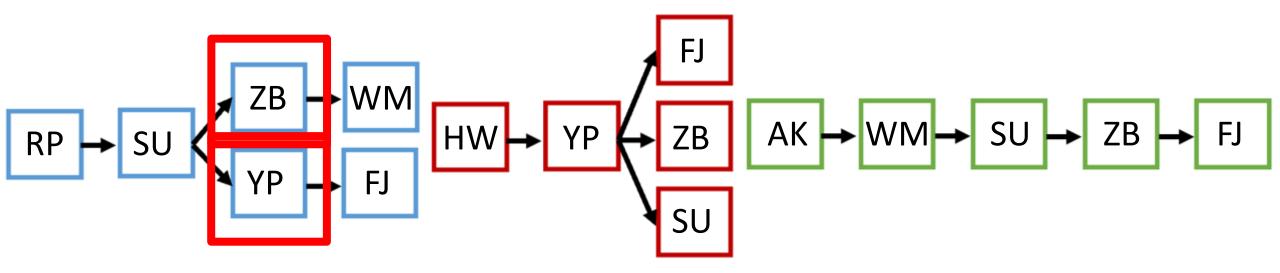


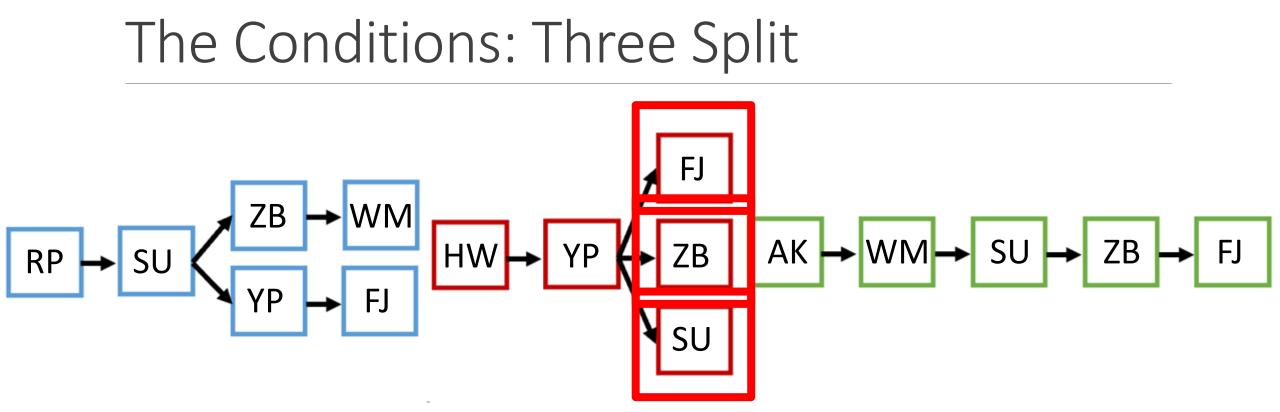
Score: Collect Data

The Conditions: Known Methods

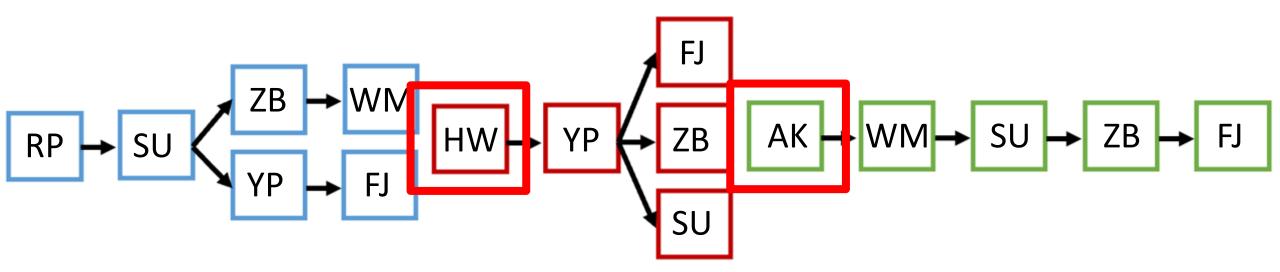


The Conditions: Two Split

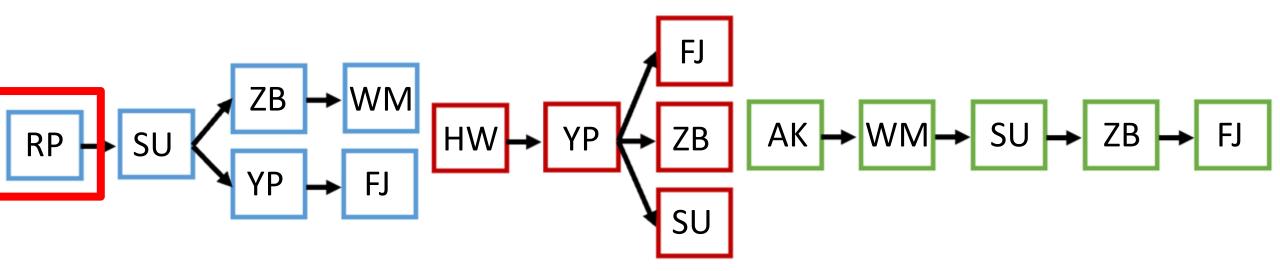


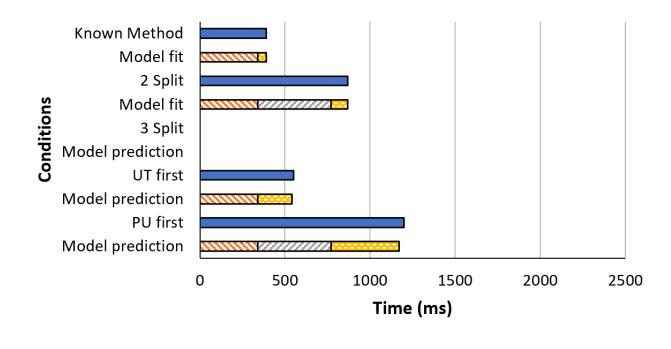


The Conditions: Unit Tasks First Method

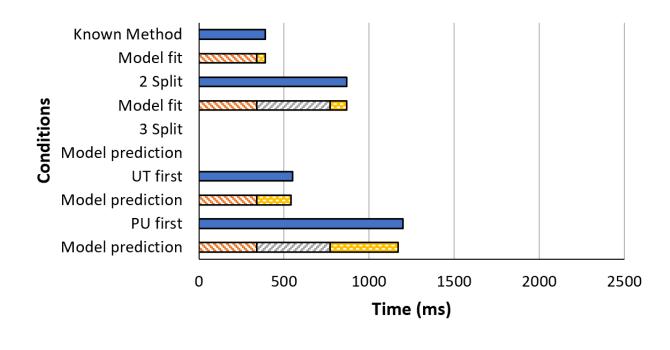


The Conditions: Planning Unit First Method

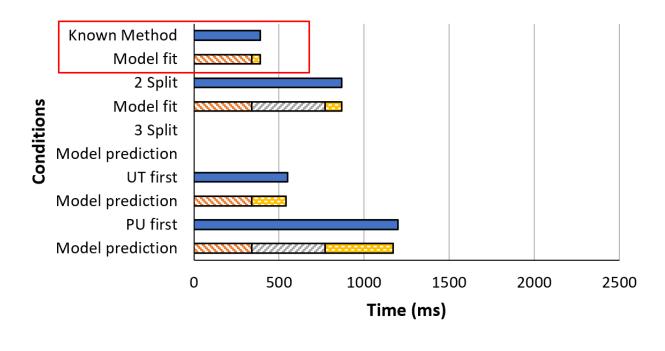




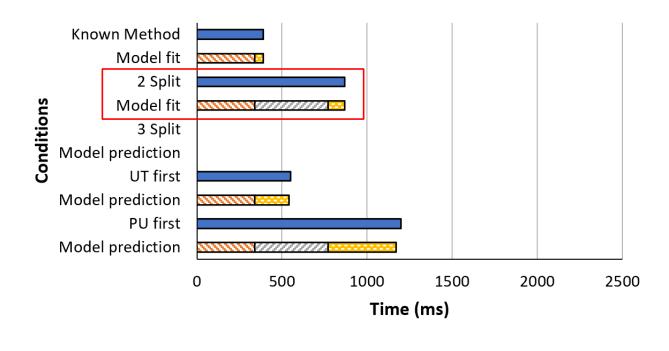
Player Motor Vision Productions



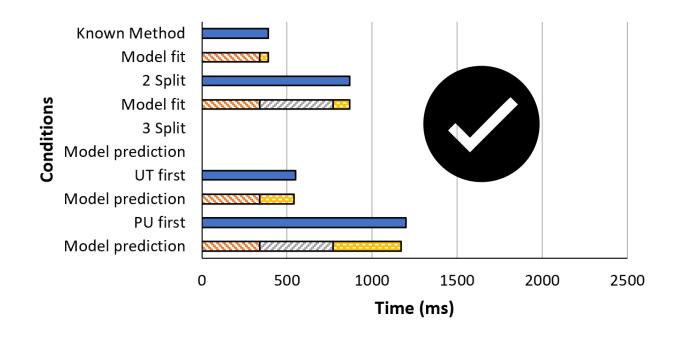
Player Motor Vision Productions



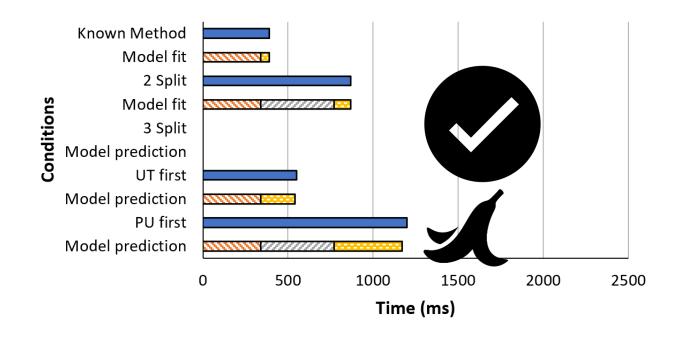
Player Motor Vision Productions



Player Motor Vision Productions



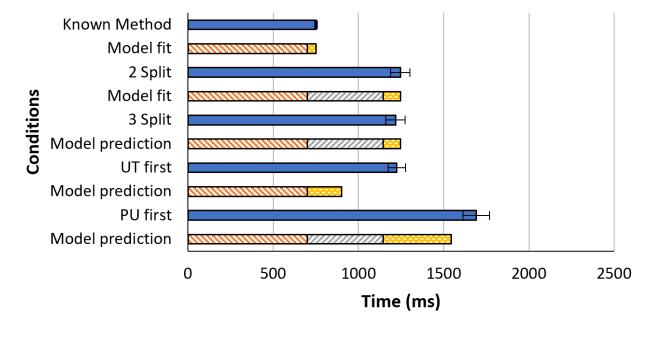
Player Motor Vision Productions



Player Motor Vision Productions

Player 1a Average Results

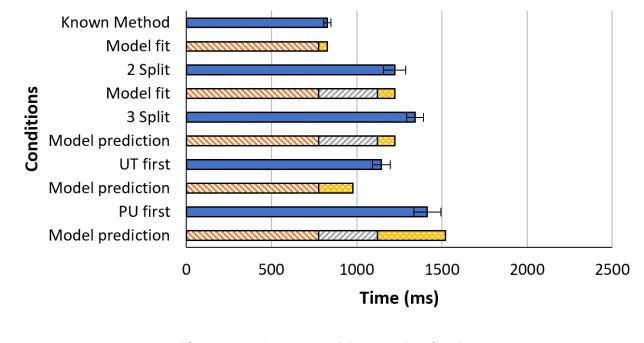
Player 1a Averages and Model Fit/Predictions



■Player ■Motor ■Vision ■Productions

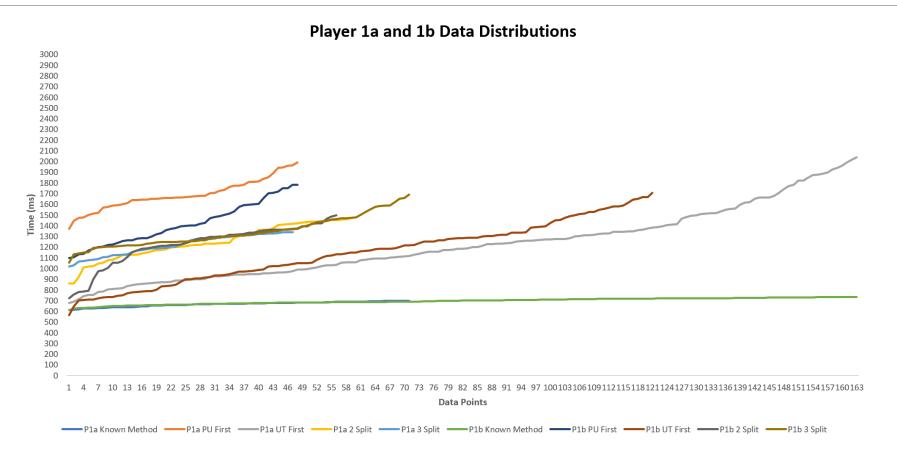
Player 1b Average Results

Player 1b Averages and Model Fit/Predictions



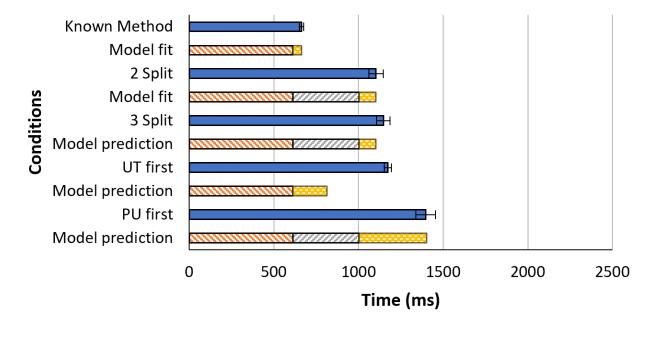
Player Motor Vision Productions

Player 1a and 1b Distribution Results



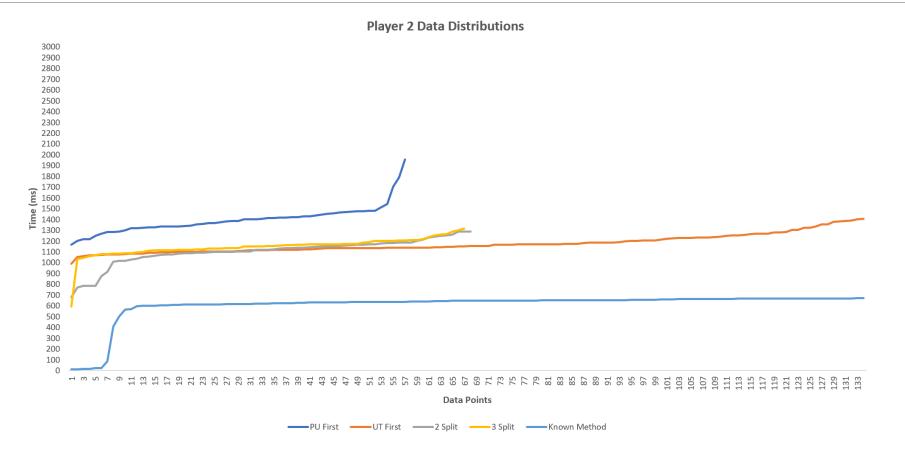
Player 2 Average Results

Player 2 Averages and Model Fit/Predictions



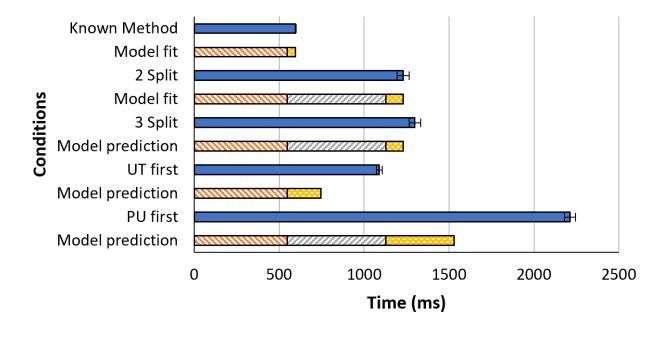
Player Motor Vision Productions

Player 2 Distribution Results



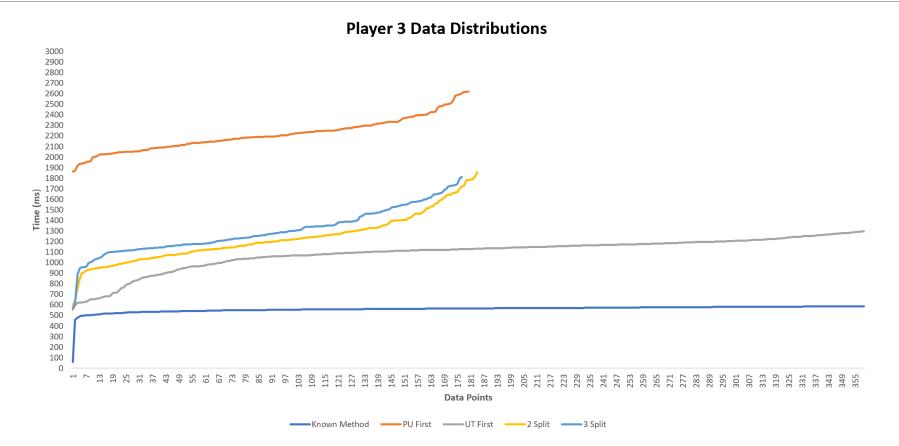
Player 3 Average Results

Player 3 Averages and Model Fit/Predictions



■ Player S Motor Vision Productions

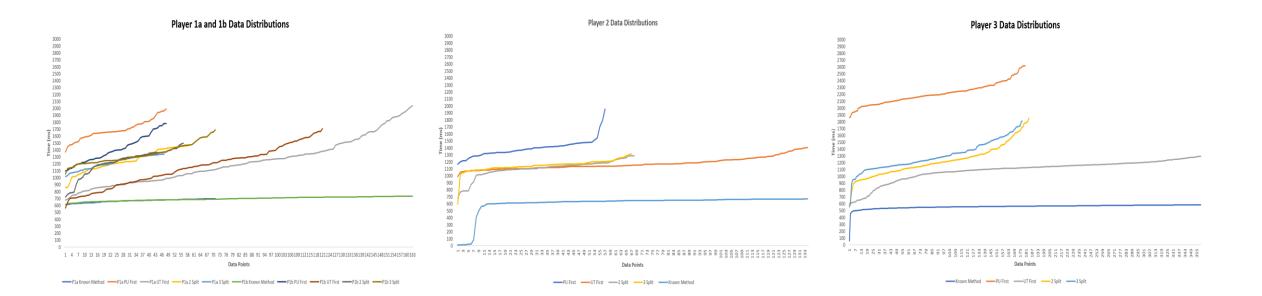
Player 3 Distribution Results



The data story

Known Methods Condition

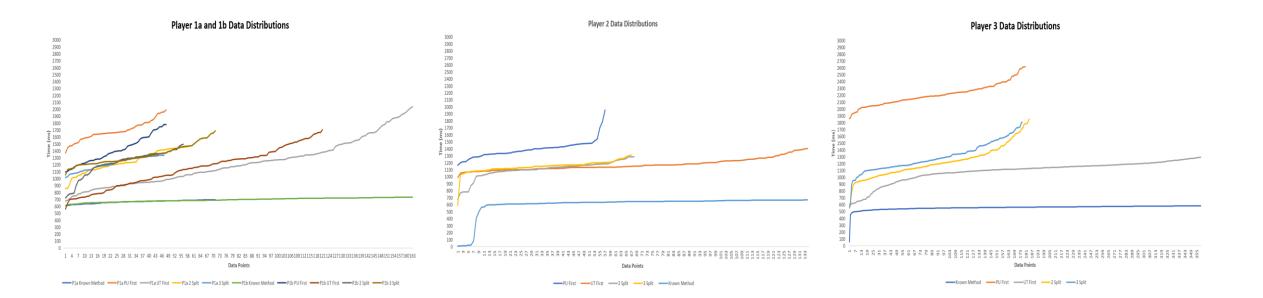
• Very consistent despite being embedded in a complex task



The data story

Two and Three Split Conditions

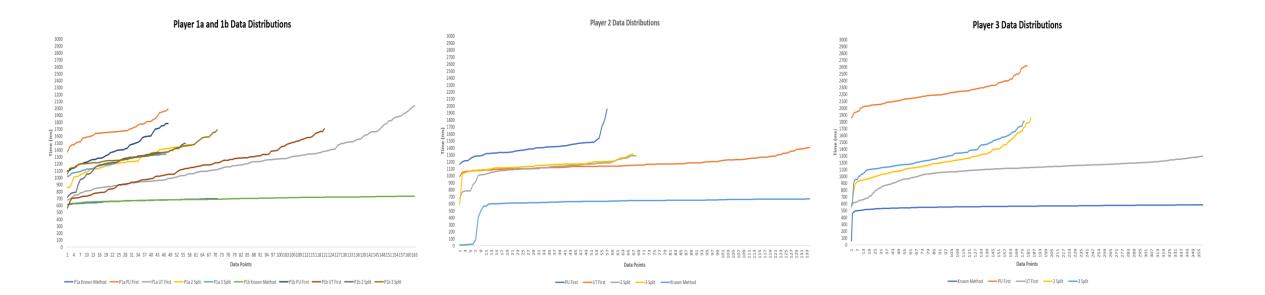
 Consistent with Schneider & Anderson (2011), Hick's "law" was not supported for our data. However, Player 3 takes longer. Some guessing occurs



The data story

Unit Task First Condition

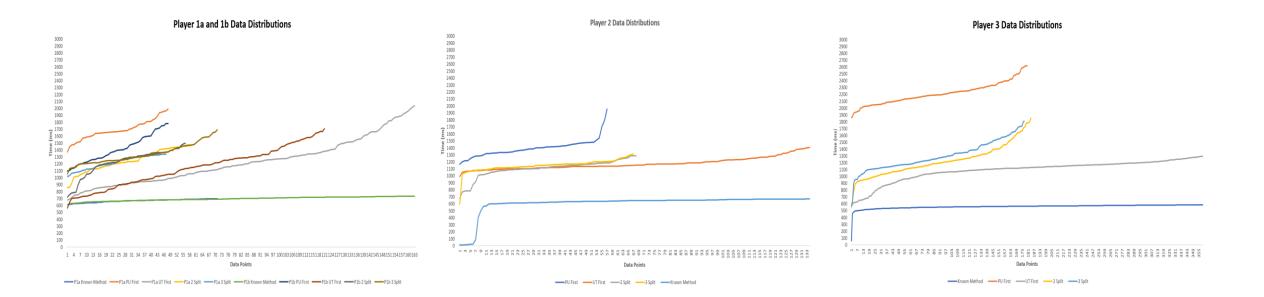
• Players made different tradeoffs



The data story

Planning Unit Condition

• Planning units are cognitively penetrable. Big source of individual differences. Hard to hold in the head



Thank You