
Between the Boxes: Rensselaer Efforts

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Panel Questions

- **What external systems?**
- **How was it done?**
 - ◆ **Network Traffic?**
 - ◆ **Info sent and received?**
- **What worked, and what didn't?**
- **Time synchronization?**

What External Systems? Where we are going

- **Scaled World for Intelligence Analysts**
 - ◆ Game-like look&feel as per SimCity™, WarCraft™, etc
- **Separate machine required to implement simBorg (black-box module for this project uses AI-based Formal Logic System that is resource intensive)**
- **GUI-interface developed by Planet 9 Studios to use advanced 3D, multimedia, innovative features**
- **Purpose of the model is to provide simulated user for automated usability testing**

What External Systems? How we are getting there

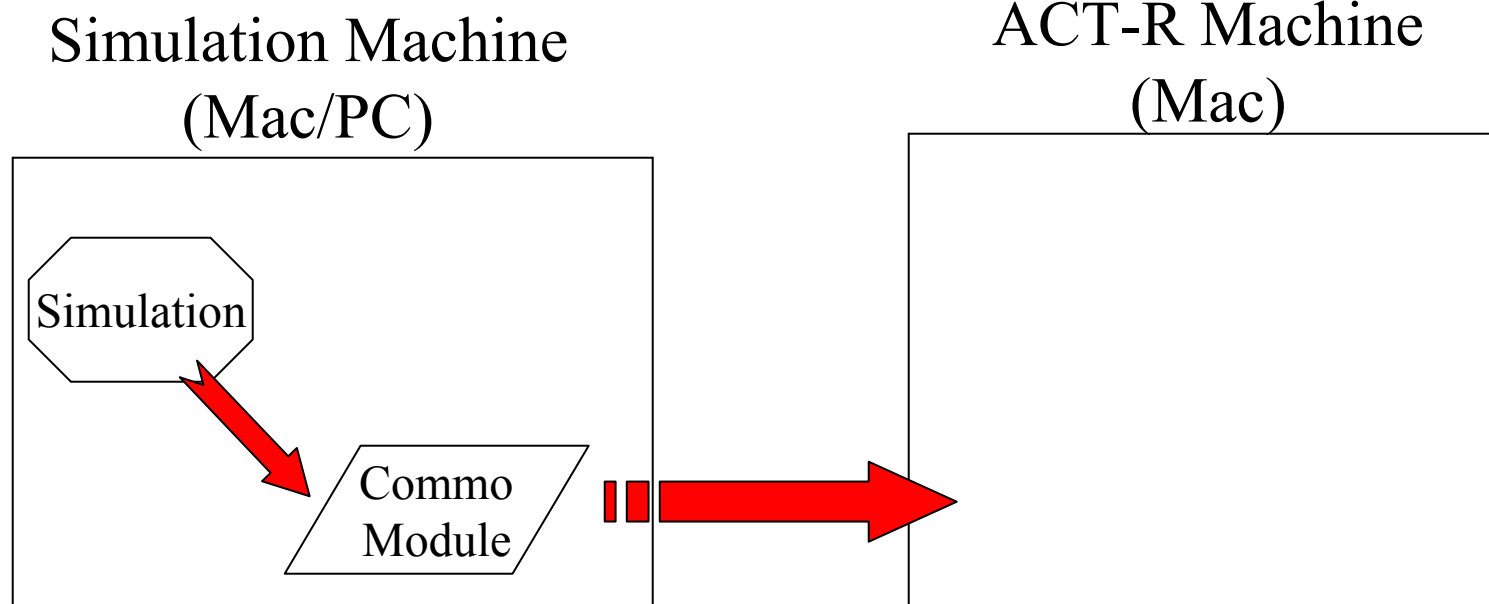
■ **Mac-to-Mac in MCL (proof-of-concept)**

- ◆ Argus Prime simulation & model
- ◆ We built both

■ **Mac-to-PC (toy system)**

- ◆ ACT-R in MCL
- ◆ Simulation in C++ under windows
- ◆ We built both

How Was It Done?



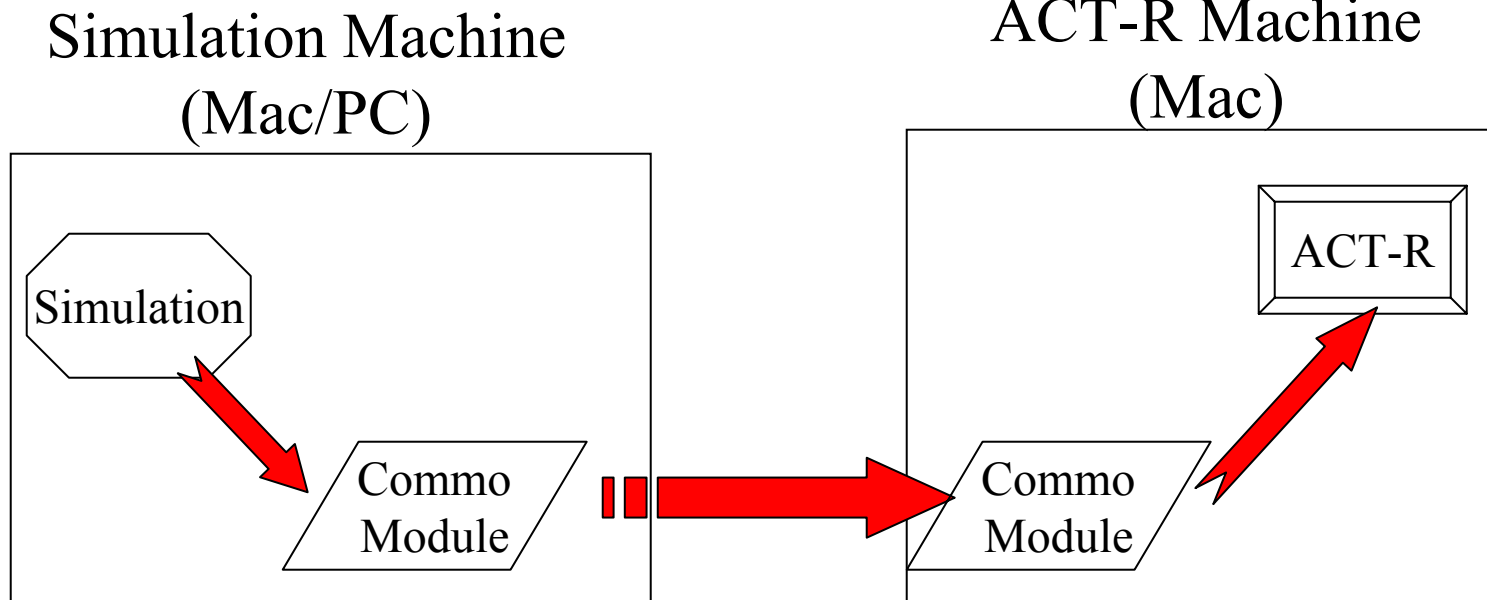
■ Simulation

- ◆ Sends text descriptions of GUI objects to Commo Module

■ Commo Module

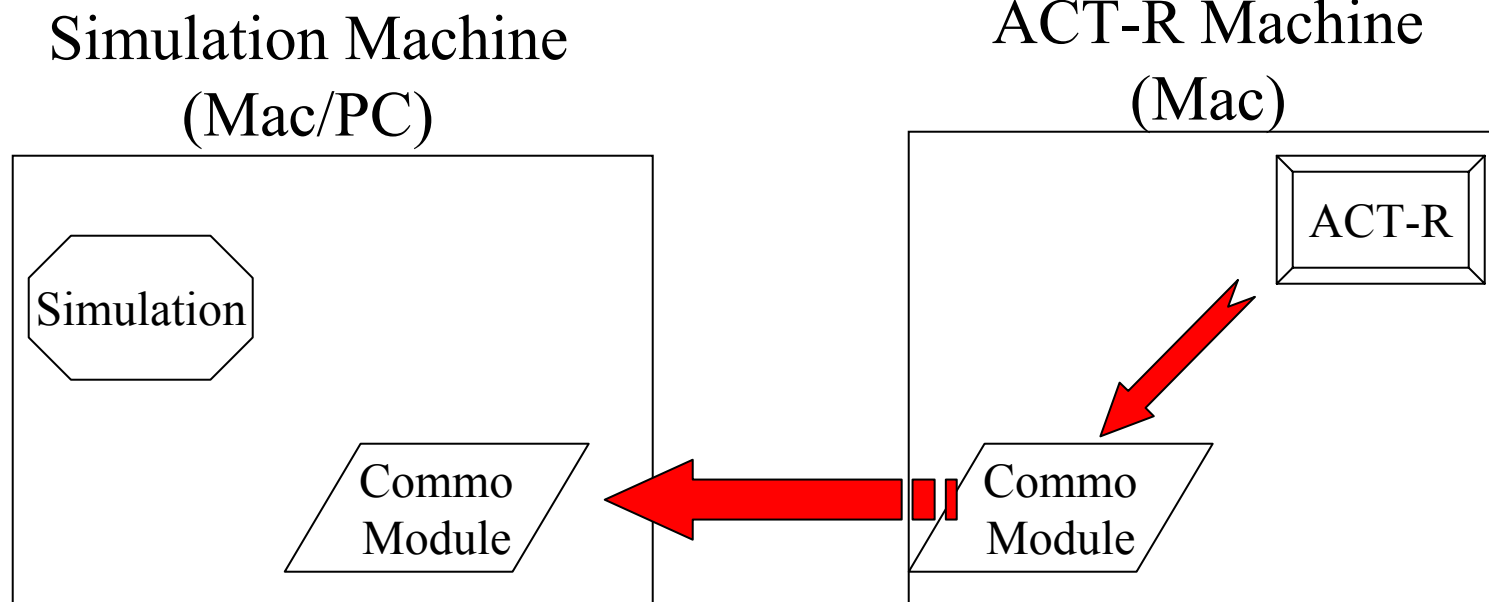
- ◆ Sends feature descriptions & mouse/cursor positions over TCP/IP (text strings) to ACT-R machine

How Was It Done?



- Commo Module(Mac machine)
 - ◆ Instantiates features
 - ◆ Updates visual memory
- ACT-R cranks on

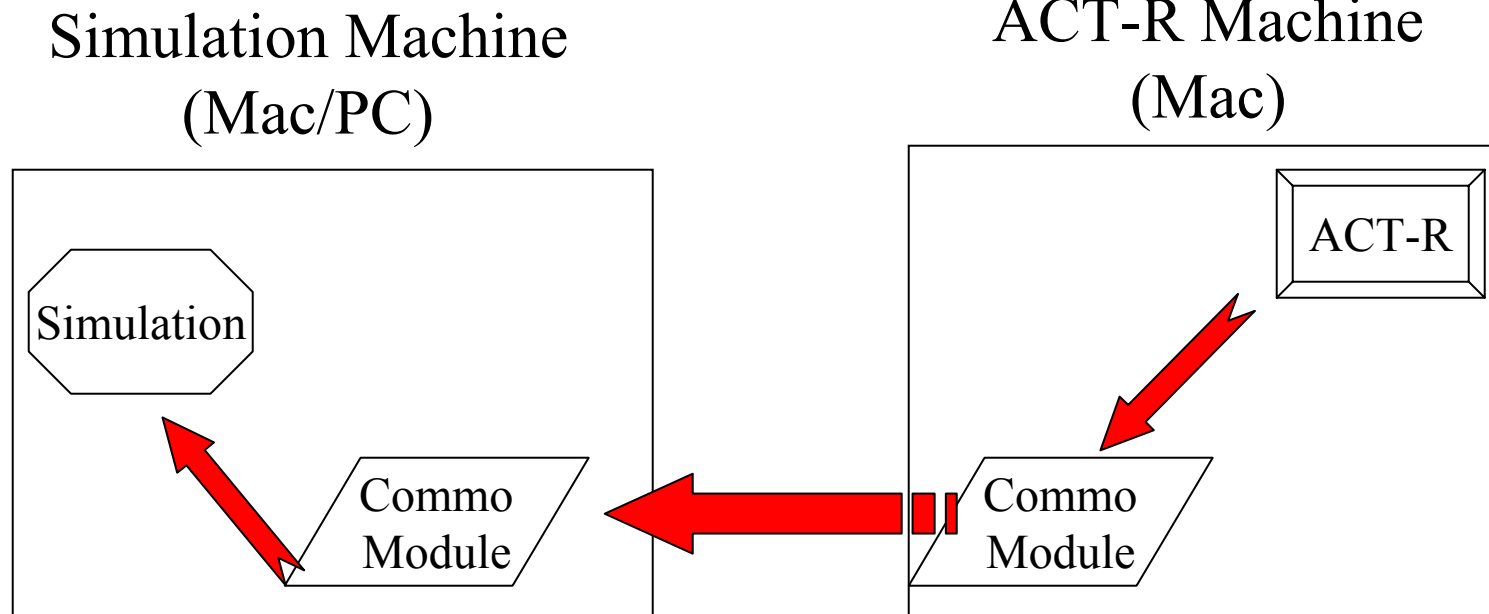
How Was It Done?



- ACT-R
 - ◆ RPM functions redefined to send messages to Commo Module

- Commo Module
 - ◆ Sends commands to Simulation Machine over TCP/IP

How Was It Done?



- Commo Module (simulation machine)
 - ◆ Makes OS call to execute RPM commands

What worked, and what didn't?

■ **Mac-to-Mac**

- ◆ **Model was more intertwined with simulation than modeler had realized**
- ◆ **Separating the two helps to keep the modeler honest!**

■ **Mac-to-PC**

- ◆ **Line endings!!**
- ◆ **Finding common ground with the developer**
- ◆ **Currently in-progress!**

Time synchronization?

- **We avoid many problems with time synchronization because our simulations run in real-time -- hence we can use the real-time mode of ACT-R**
- **Running on separate machines avoids conflict of resources that would lead to timing issues**
 - ◆ **No degradation of resources due to simulation -- makes it easier for ACT-R to keep up with a dynamic simulation in real-time**
 - ◆ **Prevents ACT-R from locking out other processes**