



Modeling the Use of Multiple Frames of Reference

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Research Objectives

- Computational model of the architecture of spatial cognition
- Embedded in ACT-R as a spatial module
- Theory-driven
 - FORMS theory based on existing empirical data
- Empirically Driven
 - Bottom-up approach
 - Spatial attention
 - Representation of objects, features, and locations
 - Object-to-object relationships and multiple frames of reference
 - Map tasks
 - Screen based objects and relations as representations of objects around you
 - Saliency, spatial updating

FORMS: Psychological Space is Segmented, Compressed, and Distorted

- Egocentric
 - Eye-centered space
 - Hand-centered space
 - Body-centered space
- Allocentric
 - World-centered space
 - Special case: screen-based

Psy Space is Compressed: Maps of Saliency

- Each segment of space is represented as a map of saliency
- Represents
 - behaviorally significant information (top-down influence)
 - perceptually outstanding information

Objects, Features, and Location

- How are objects, object features and object locations represented?
- ACT-R uses a unified representation:

Drawing93

isa DRAWING

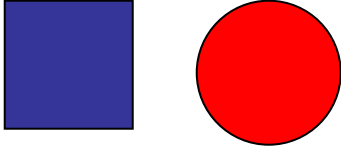
screen-pos Loc41

value Tie

status nil

color Black

Evidence for Independent Encoding of Object Features: Illusory Conjunctions

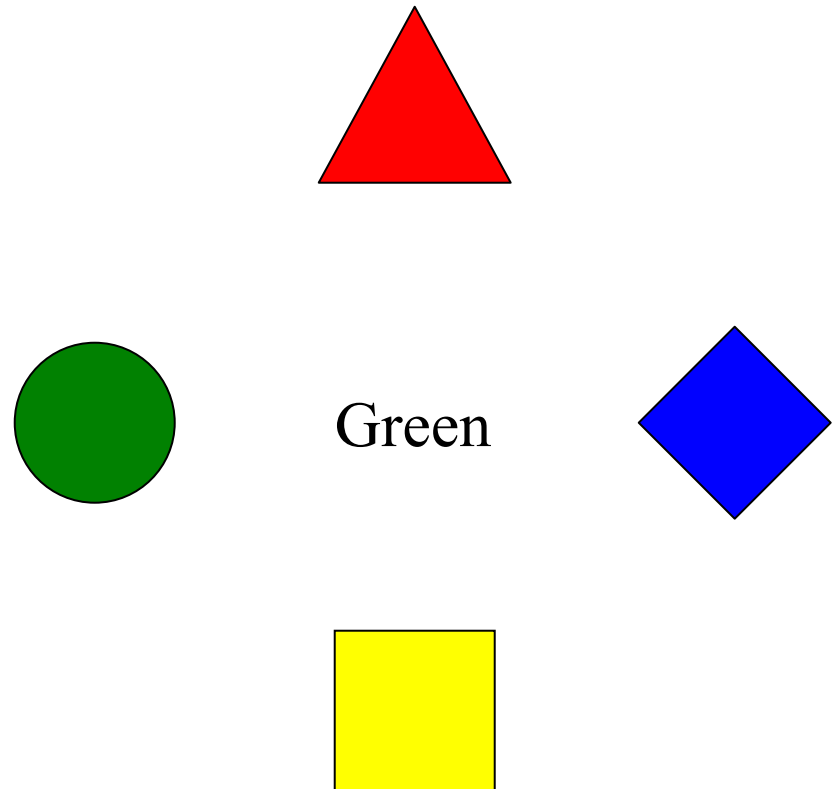
- Typically brief presentation time (50-120ms) with mask
 - See: A blue square and a red circle.
 - Report: blue circle
- May be due to
 - Misperception
 - Binding errors
 - Error in recombining features from memory
- Memory Conjunction Errors
 - Even with no mask and long (5 sec) presentation time

Evidence for Independent Encoding: Memory Conjunction Errors

- Longer presentation times, no mask
 - Stefurak and Boynton (1986)
 - 5 colored forms for 5 seconds, no mask
 - Controlled for verbalization using mental arithmetic task
 - 1 old or new target
 - Found complete independence of color and shape (No conjunction memory)

Nissen Task (1985)

- Stimuli:
 - 4 shapes
 - 4 colors
 - 4 locations
- Duration 60-190 ms
- Mask
- Replaced with cue:
 - Conditions:
 - Color cue
 - Location cue

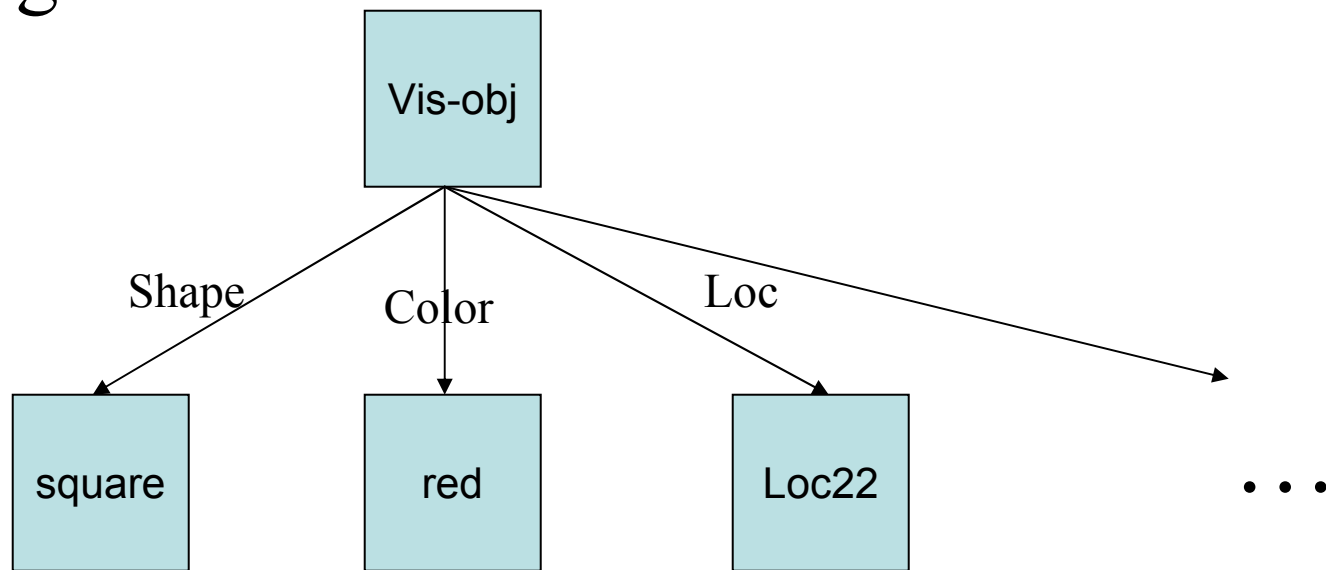


Nissen Results

- Location cue
 - Correct recall of color and shape is statistically independent
- Color cue
 - Correct recall of shape is statistically dependent on recall of location
- Nissen argued that features were stored independently, but tagged or indexed by location

ACT-R Predicts Dependence

- ACT-R produces an integrated representation
- Predicts complete dependence of color and shape given location



Distributed, Location-Bound Repr.

- Visual representation is feature based, but features are bound by spatial location
- Location may use one or more FOR

Object-to-Object Spatial Relations: The Milner Task

- Developed by Milner and Colleagues (1997, 1999)
- Explores use of different frames of reference for object locations
 - screen-based
 - landmark-based
 - object-based
- Early computation vs late computation
 - What kind of spatial relationships are available early in the process (and should be provided architecturally in modeling)?

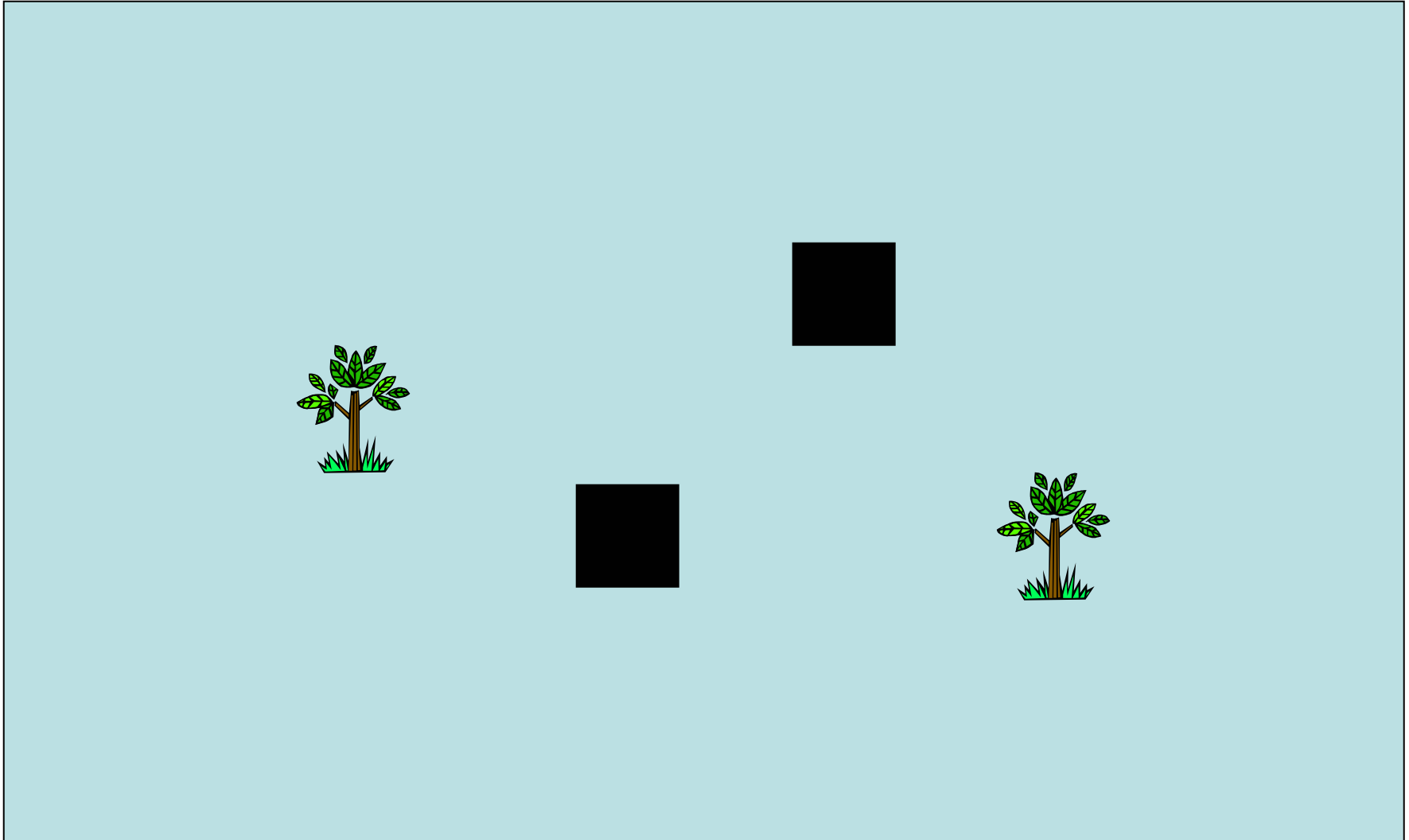
Design: Study Phase



Testing: Fixed-No cue



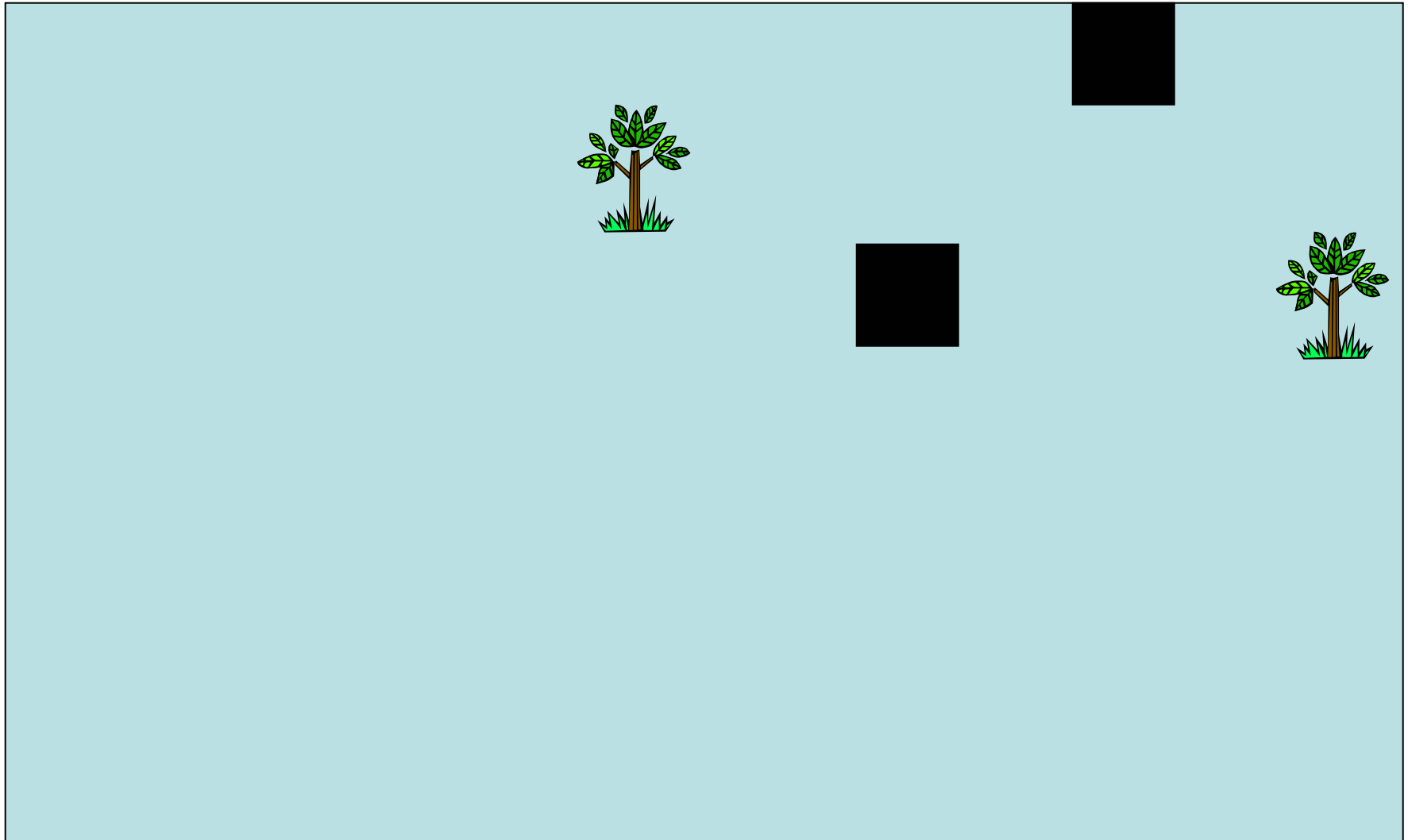
Testing: Fixed-Landmark



Testing: Fixed-Object



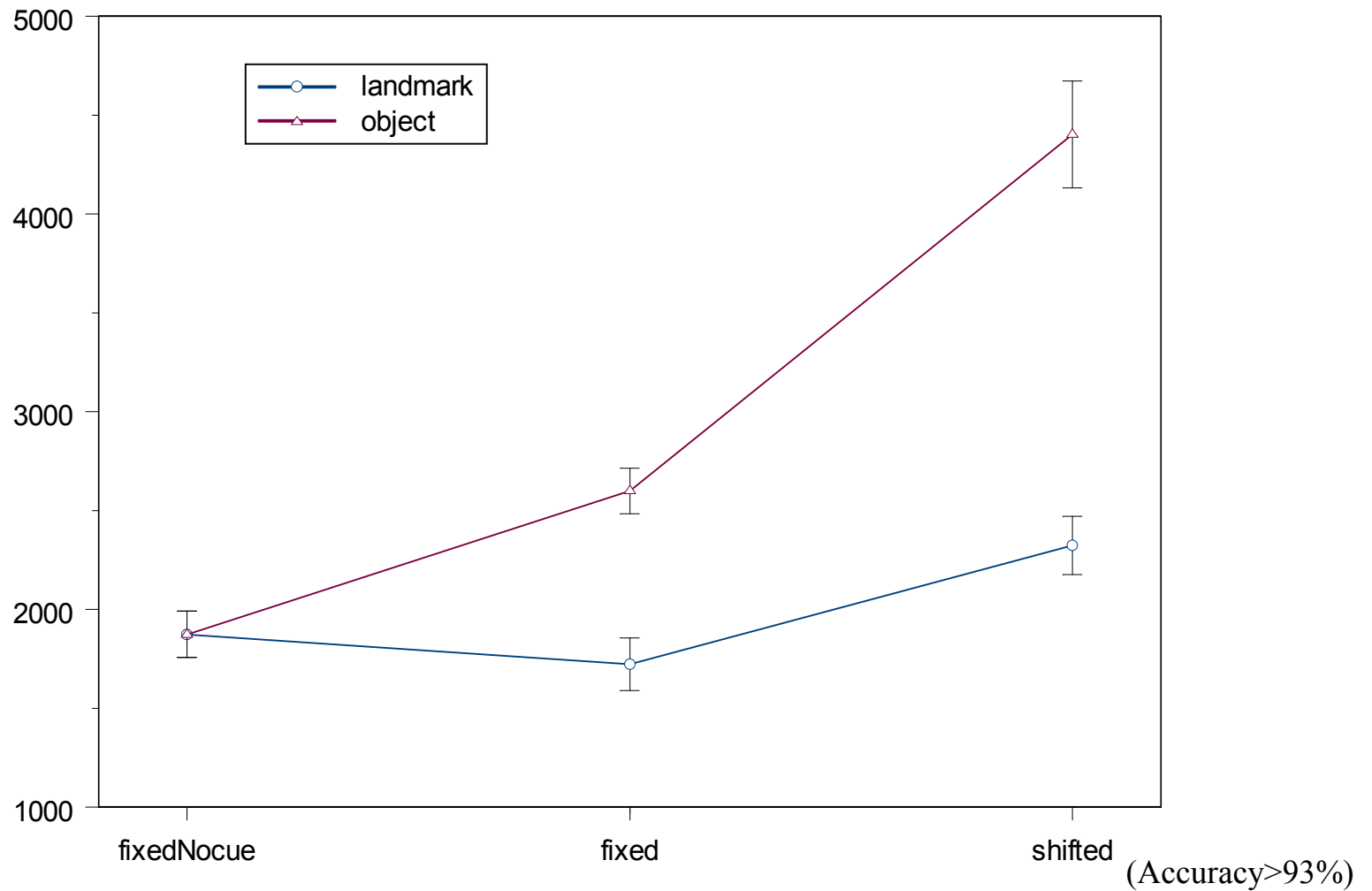
Testing: Shifted-Landmark



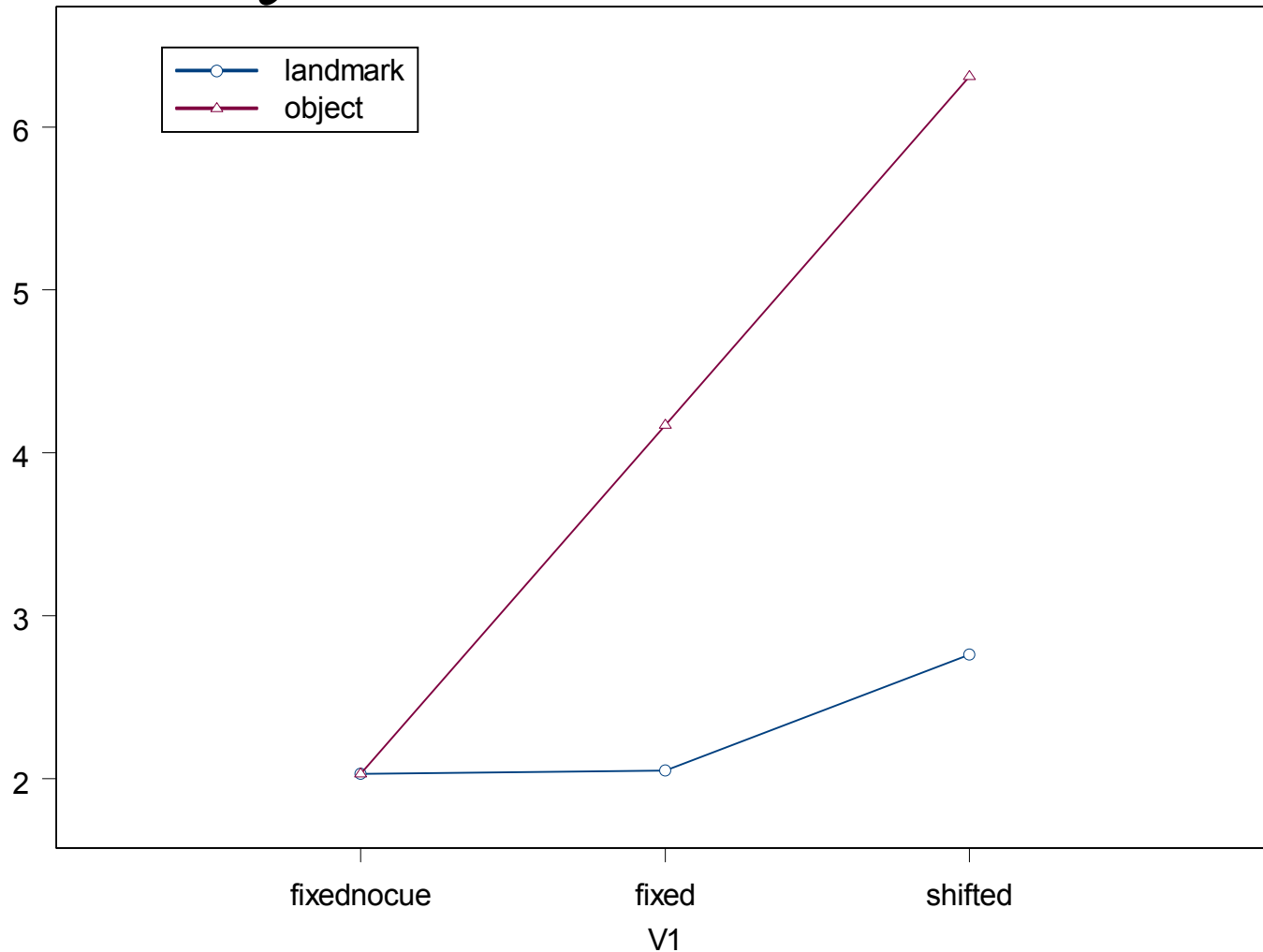
Testing: Shifted-Object



Experiment 1: RT data



Experiment 1: Eye Fixation Data



Which Object-to-Object Relations and When?

- Our solution:
 - Switching attention from one object to another builds a spatial relation between the two objects
 - Attending to a blank space returns a “blank” visual object
 - This also provides a trace of visual attentional shifts

ACT-R Model Strategy: Study

- Find and attend to the study drawing
- Note that the visual object (drawing) is a study object
- Attend to one landmark (Results in a spatial relation)
- Retrieve relation and note it as a study relation
- Reattend drawing
- Attend to second landmark
- Retrieve relation and note it as a study relation

Model Strategy: Fixed-no cue and Fixed-Landmark

- Find and attend to a drawing
- Retrieve the study version of the drawing
- If locations match, click drawing
- Otherwise,
 - Find and attend to other drawing and click it

Model Strategy: Shifted Landmark

- Find and attend to a drawing
- Find and attend to a landmark
- Retrieve the spatial relation just created between the drawing and landmark
- Try to retrieve a similar study spatial relation (same angle and distance)
- If study relation is retrieved and matches the test relation, then reattend drawing and click it
- Otherwise, find, attend and click the other drawing

Model Strategy: Fixed-Object

- Search for target-distractor drawing
 - Find and attend to a drawing
 - Find and attend to another unattended drawing
 - If the drawings are the same, pair is found, otherwise use current drawing as next possible target-distractor drawing

Fixed Object Strategy, cont...

- Retrieve a study drawing matching the currently attended drawing
- If the retrieved drawing has the same location, click it
- Otherwise, attend to the other drawing and click it

Model Strategy: Shifted-Object

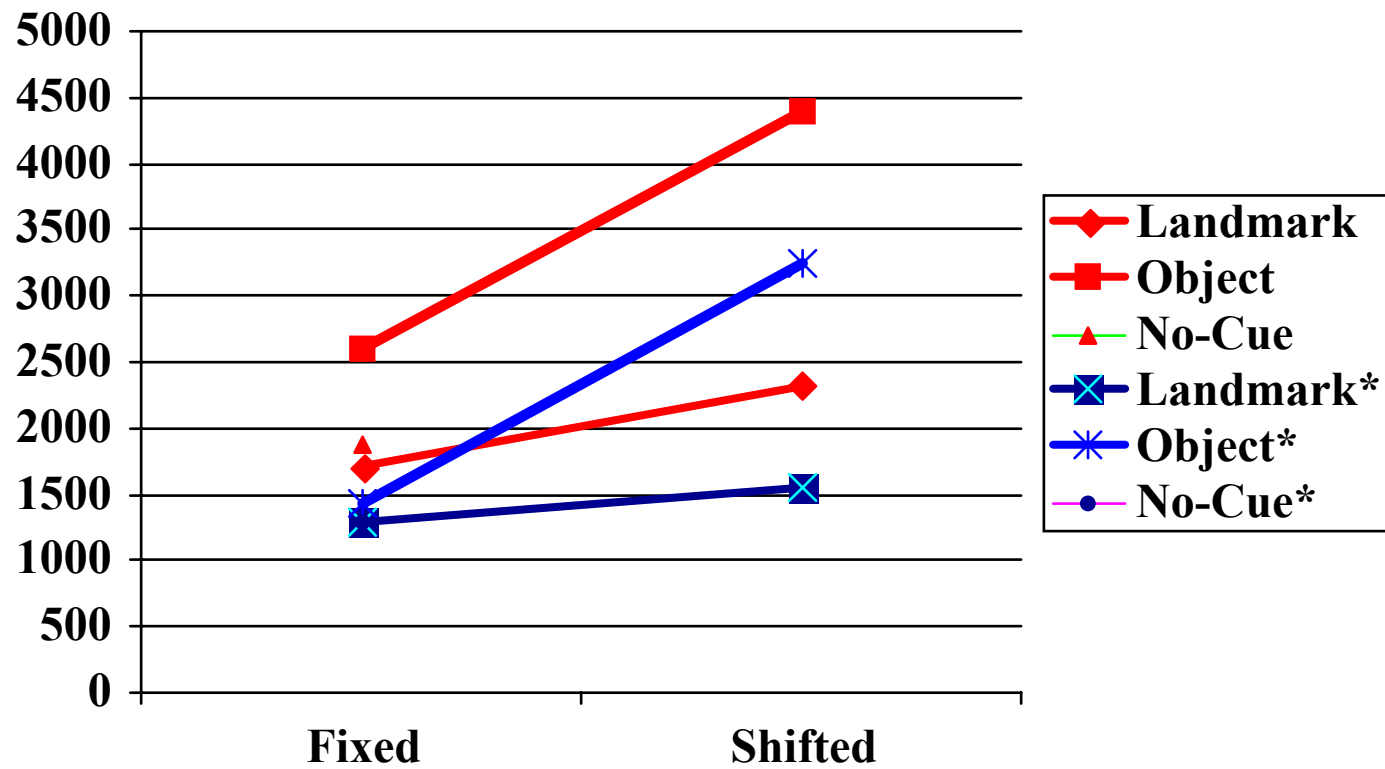
- Search for target-distractor pair
- Retrieve the study version of the drawing
- Retrieve a study object-to-object relation for the study drawing
- Attend to a cue drawing
- Use the retrieved study relation to attend to the expected location of one of landmarks
- Shift attention from this location to the cue drawing
- Retrieve the resulting “landmark” to anchor relation
- Try to retrieve a similar study relation
- If study relation matches test relation, reattend target drawing and click, otherwise attend to other duplicate drawing and click

Testing: Shifted-Object



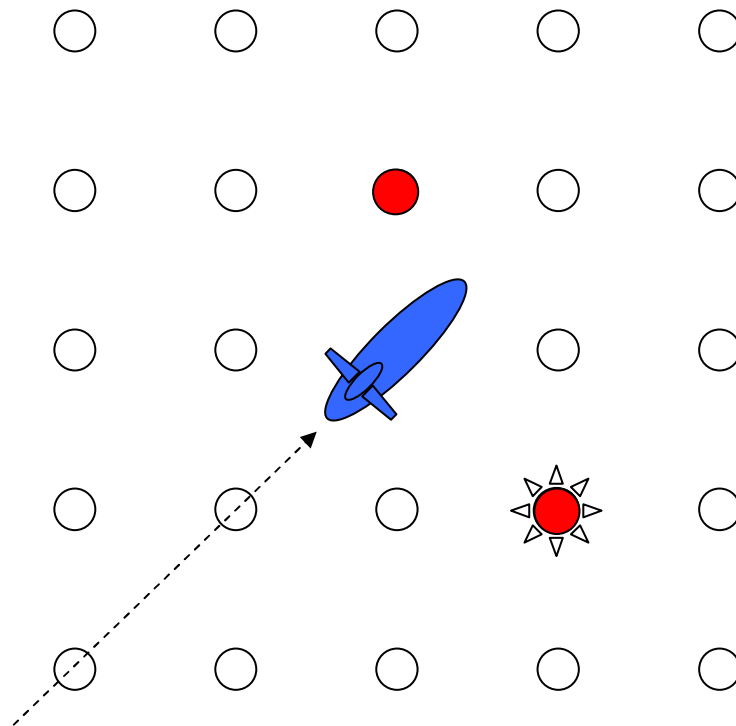
Results

$R^2=0.92$



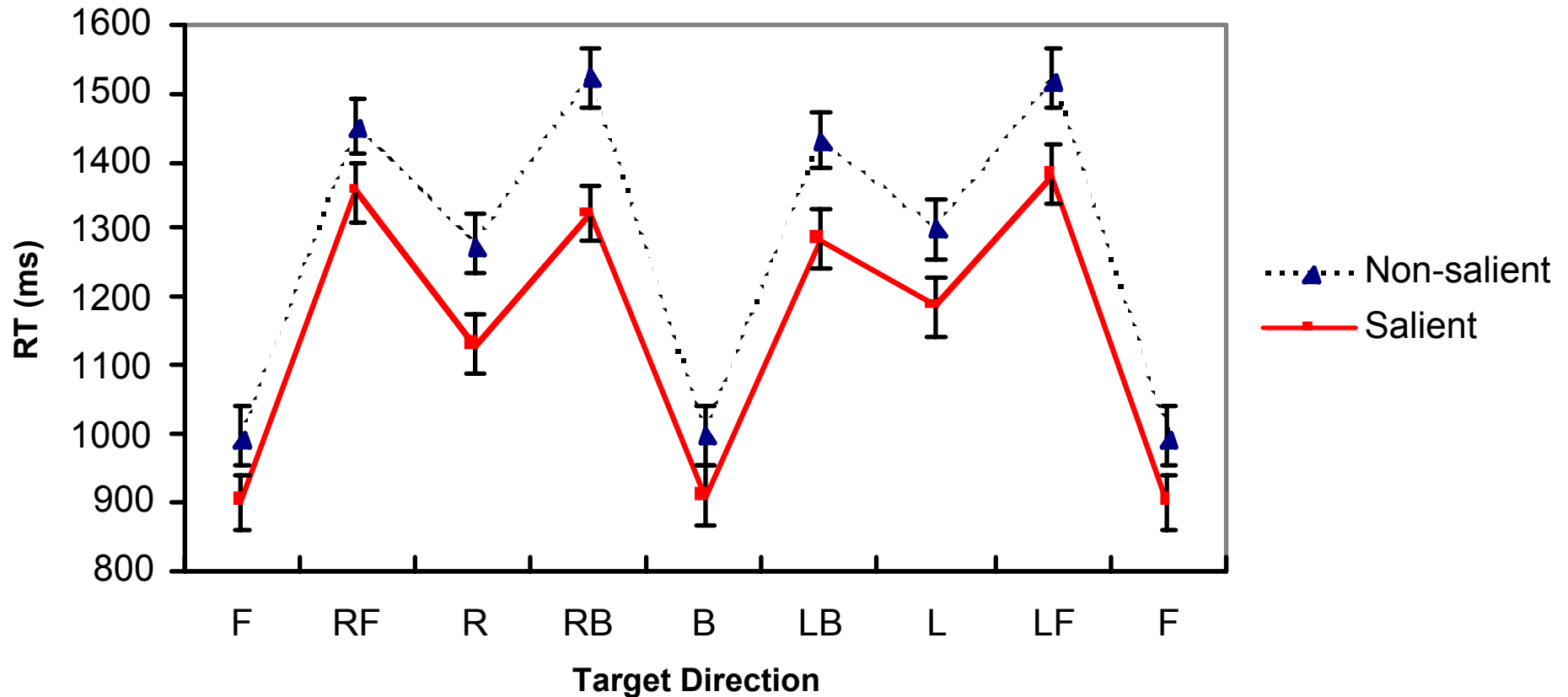
Map Tasks: Saliency, Multiple FOR, Movement

- With Yanlong Sun and Ye Yuan
- Experiment 1

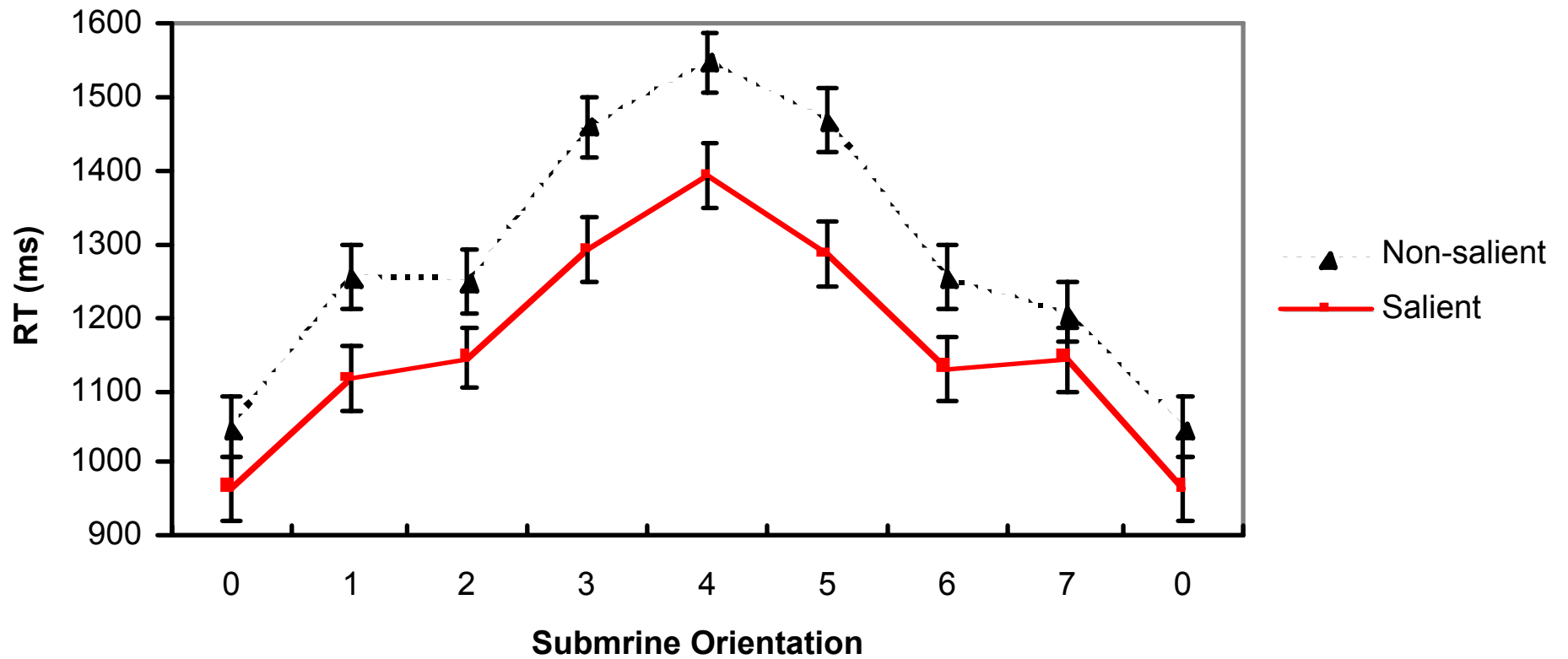


Exp 1 Results: Saliency Effect

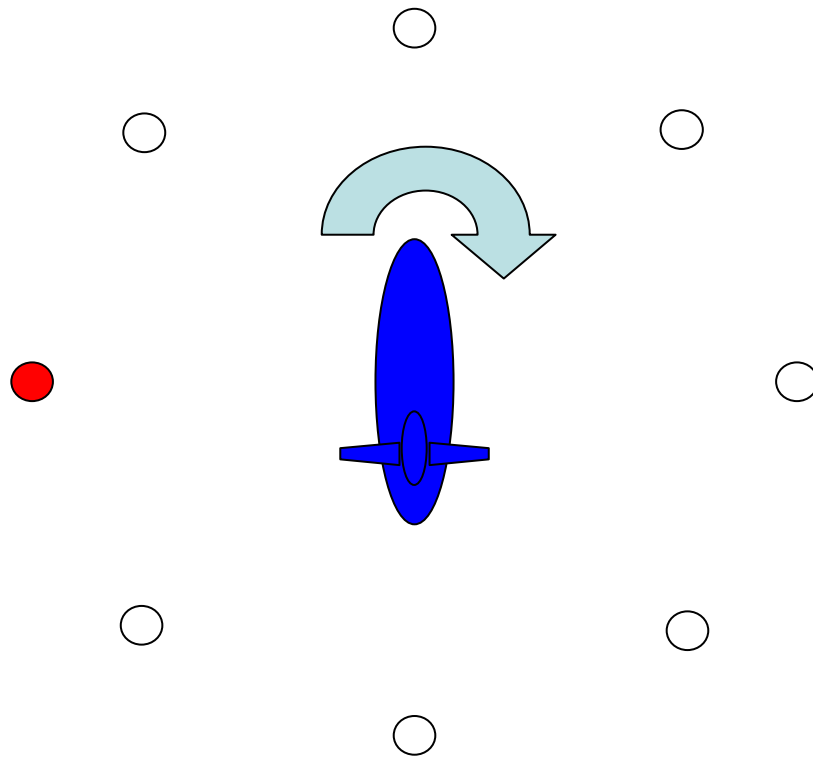
Target Direction Effect



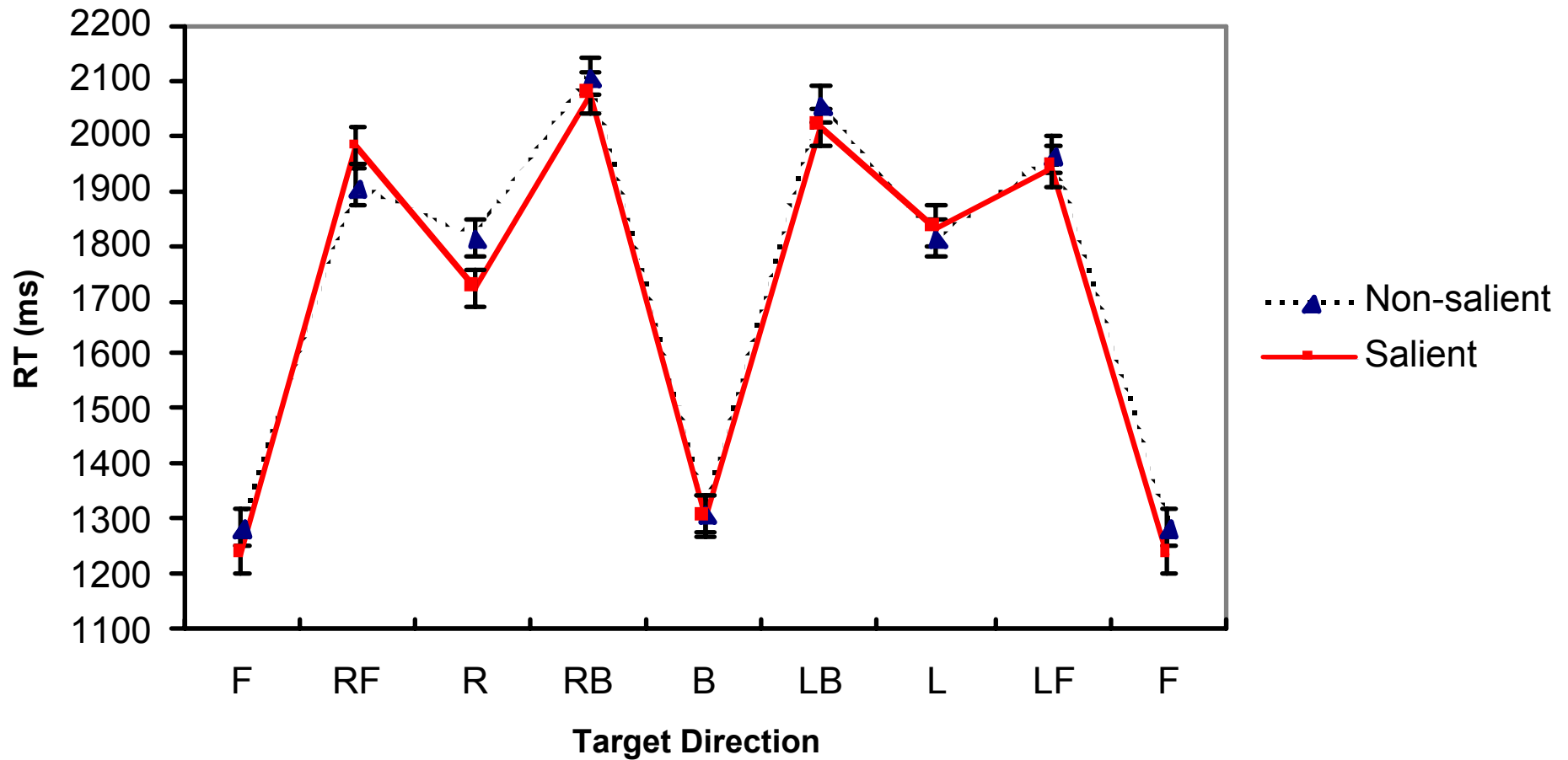
Exp 1 Results: Orientation Effect



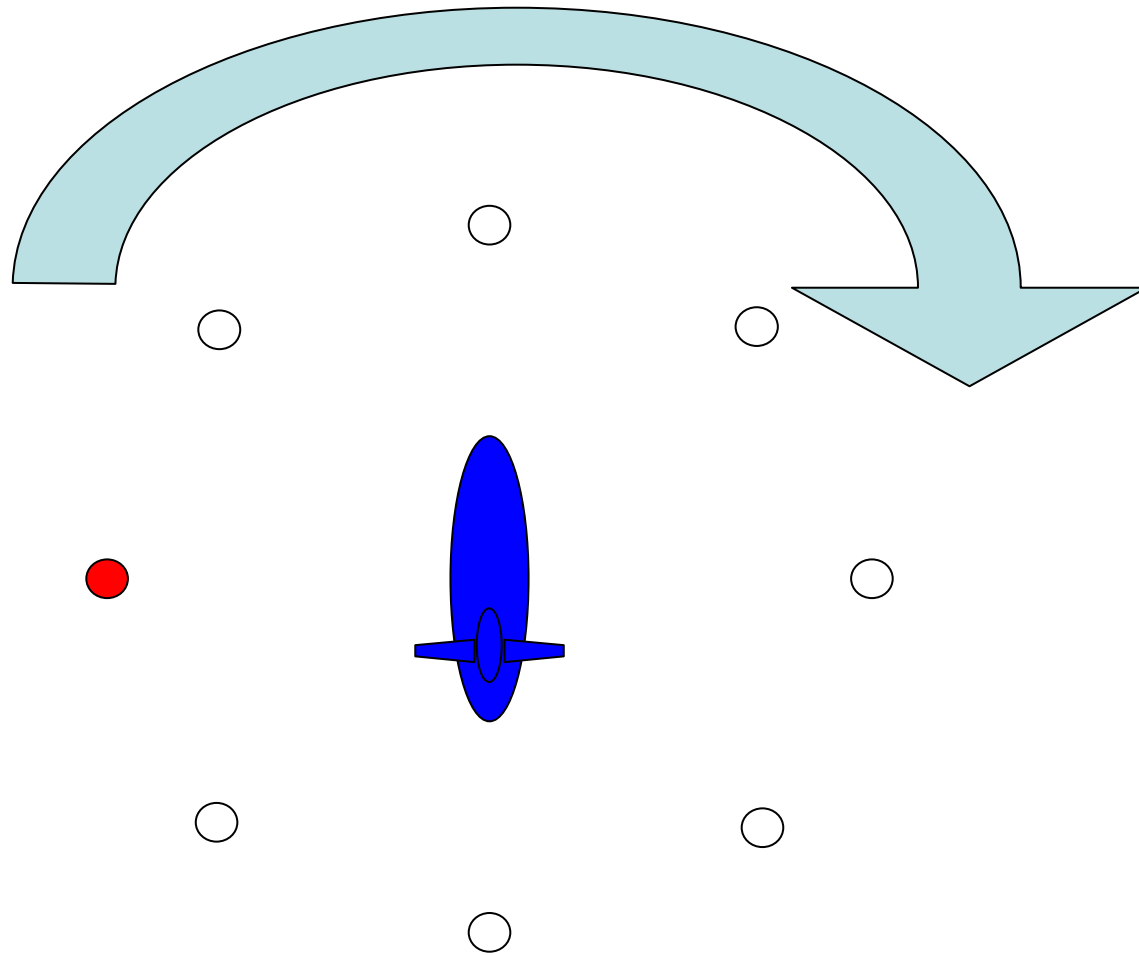
Experiment 2: Rotating FOR



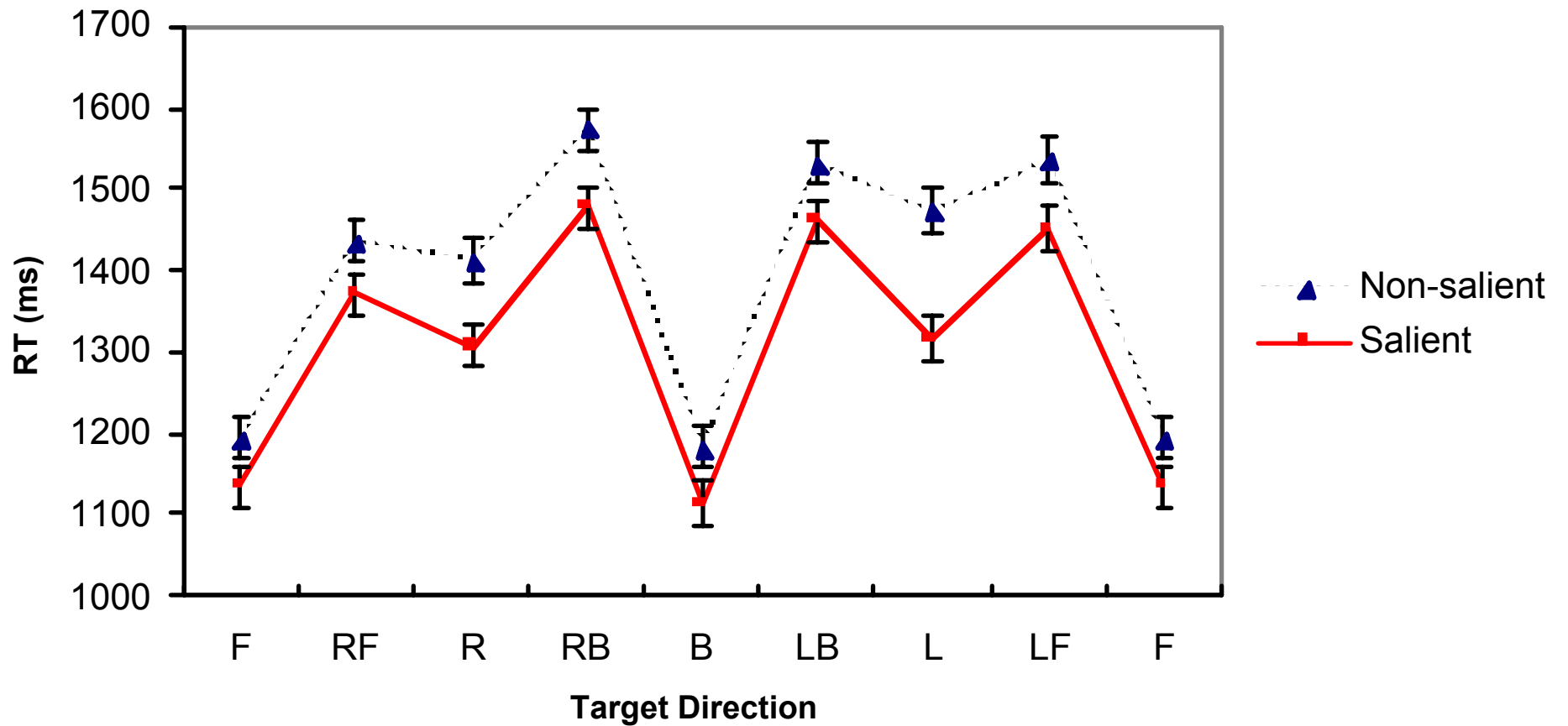
Exp 2 Results: No Saliency Effect



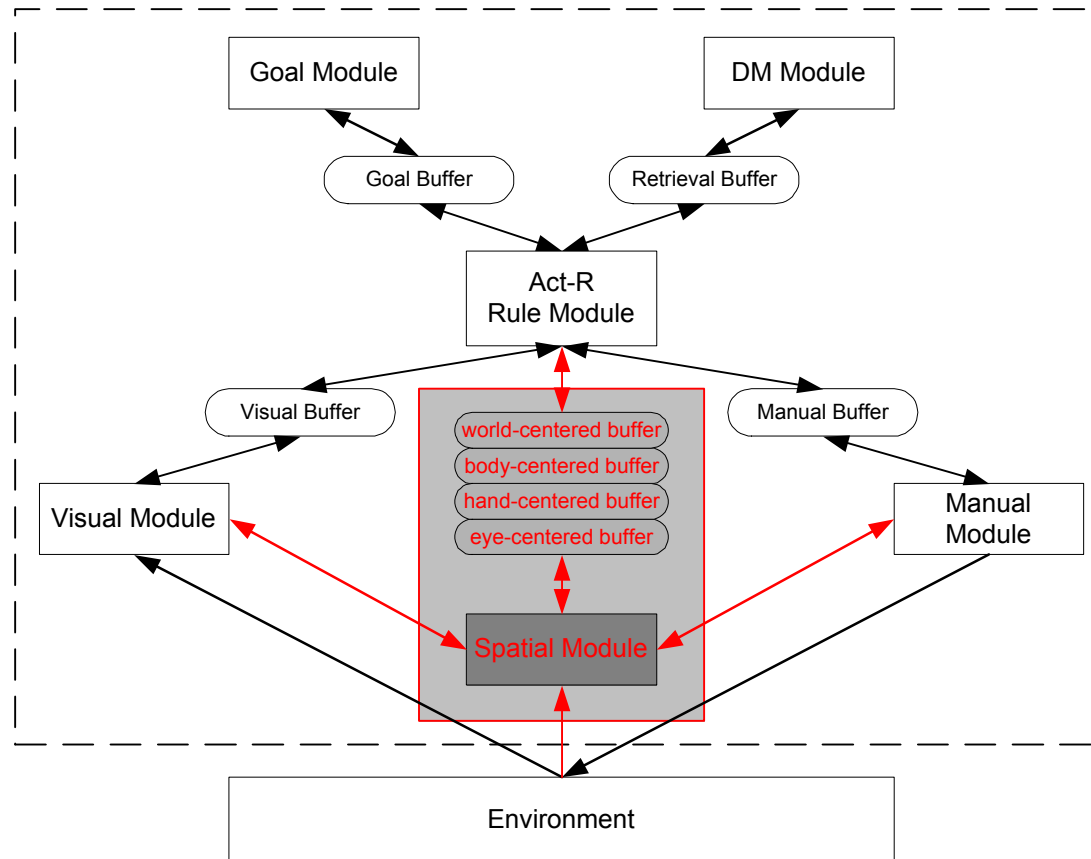
Experiment 3: Rotating Targets



Saliency Effect Returns



The Spatial Module



Key Features

- Visual Buffer: visual features
- Spatial buffers: Spatial location only
- Buffers (including visual buffer) are synchronized by default on finding locations
 - But looking at one location and pointing to another is possible
- Can find and attend to an empty spatial location
- When attention is moved from one location to another, a chunk representing the spatial relationship of the two is automatically generated.
- Different buffers with different frames of reference may explain many neuropsychological problems.
 - Patient who can name an object but cannot point to it: working visual module, but damaged hand-centered spatial representation.
- Version 1-alpha, working only with MCL.

Example 1

;; find a red object on the screen and point to it

```
(p find-red-object-location
  "find-red-object-location"
  =goal>
  ISA finding-and-pointing
  state finding
==>
=goal>
  state pointing
+visual-location>
  ISA visual-location
  kind something
  color red
)
```

```
(p point-to-it
  "point-to-it"
  =goal>
  ISA finding-and-pointing
  state pointing
=hand-centered-location>
  ISA hand-centered-location
==>
=goal>
  state done
+manual>
  ISA point-hand
  hand right
  location =hand-centered-location>
)
```

Example 2

```
;; find the center of the screen  
;; (nothing there) and look at it
```

```
(p find-location  
  "find-location"  
  =goal>  
    ISA finding-and-looking  
    state finding  
==>  
  =goal>  
    state looking  
  +screen-based-location>  
    ISA screen-based-location  
    screen-x 512  
    screen-y 384  
)
```

```
(p look-at-it  
  "look-at-it"  
  =goal>  
    ISA finding-and-looking  
    state looking  
  =eye-centered-location>  
    ISA eye-centered-location  
==>  
  =goal>  
    state done  
  +visual>  
    ISA visual-object  
    screen-pos =eye-centered-location>  
)
```


How does the approach support...

- Spatial localization of objects relative to self
 - Eye, body, and hand centered buffers
- Spatial relations among objects
 - World-centered buffer and shift of spatial attention
- Navigation
- Imaginary spatial problem solving
 - Spatial module will support functions for rotation, translation, etc.

Effects on Spatial Problem Solving

- Attentional shift method for producing object-to-object relationships affects strategies for
 - studying spatial arrays
 - comparing current spatial configurations to past configurations
- Requires deliberate effort to tag spatial objects and relations with contextual information (e.g., study, test)