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# ***Between the Boxes: Rensselaer Efforts***

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**Rensselaer** | Cognitive  
Science

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## ***Panel Questions***

- **What external systems?**
- **How was it done?**
  - ◆ **Network Traffic?**
  - ◆ **Info sent and received?**
- **What worked, and what didn't?**
- **Time synchronization?**

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## ***What External Systems? Where we are going***

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- **Scaled World for Intelligence Analysts**
  - ◆ Game-like look&feel as per SimCity™, WarCraft™, etc
- **Separate machine required to implement simBorg (black-box module for this project uses AI-based Formal Logic System that is resource intensive)**
- **GUI-interface developed by Planet 9 Studios to use advanced 3D, multimedia, innovative features**
- **Purpose of the model is to provide simulated user for automated usability testing**

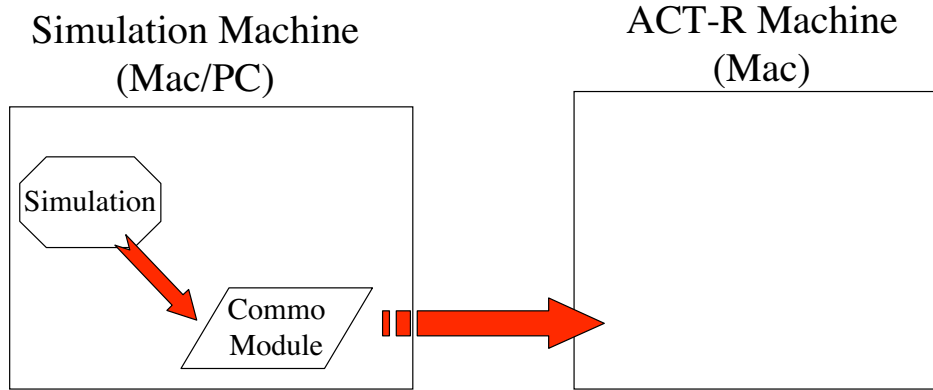
## ***What External Systems? How we are getting there***

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- **Mac-to-Mac in MCL (proof-of-concept)**
  - ◆ Argus Prime simulation & model
  - ◆ We built both
- **Mac-to-PC (toy system)**
  - ◆ ACT-R in MCL
  - ◆ Simulation in C++ under windows
  - ◆ We built both

# How Was It Done?

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## ■ Simulation

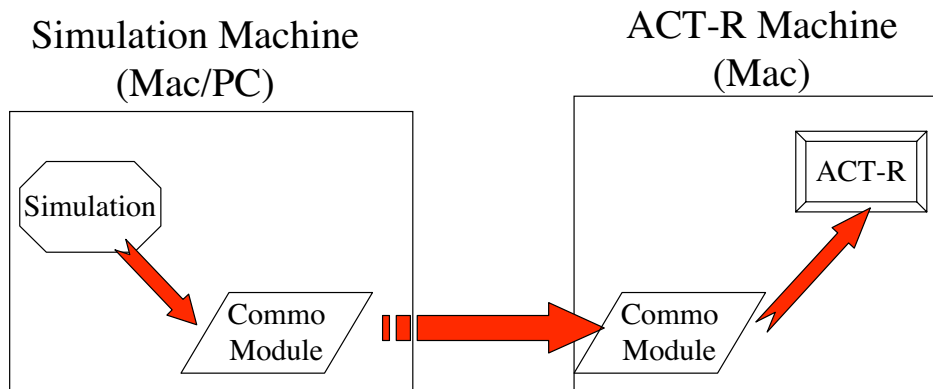
- ◆ Sends text descriptions of GUI objects to Commo Module

## ■ Commo Module

- ◆ Sends feature descriptions & mouse/cursor positions over TCP/IP (text strings) to ACT-R machine

# How Was It Done?

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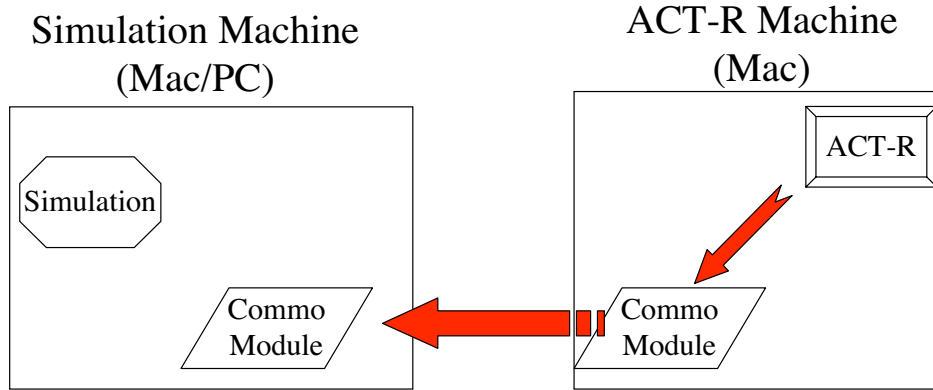
## ■ Commo Module(Mac machine)

- ◆ Instantiates features
- ◆ Updates visual memory

## ■ ACT-R cranks on

# How Was It Done?

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- ACT-R

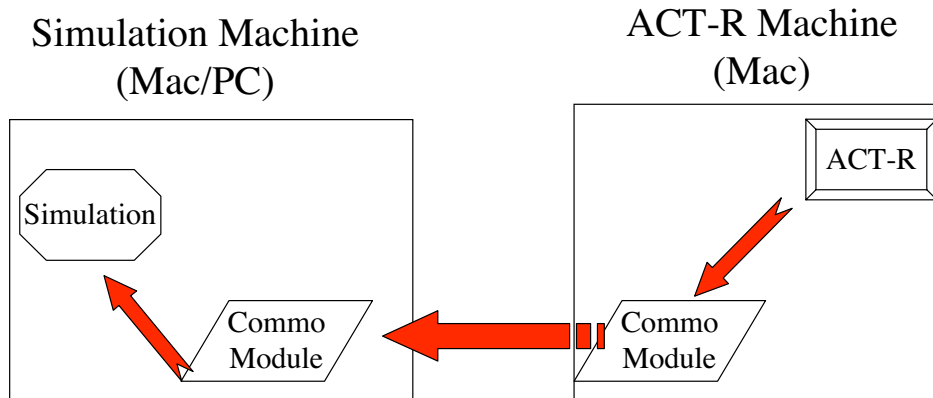
- ◆ RPM functions redefined to send messages to Commo Module

- Commo Module

- ◆ Sends commands to Simulation Machine over TCP/IP

# How Was It Done?

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- Commo Module (simulation machine)

- ◆ Makes OS call to execute RPM commands

# *What worked, and what didn't?*

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## ■ Mac-to-Mac

- ◆ Model was more intertwined with simulation than modeler had realized
- ◆ Separating the two helps to keep the modeler honest!

## ■ Mac-to-PC

- ◆ Line endings!!
- ◆ Finding common ground with the developer
- ◆ Currently in-progress!

# *Time synchronization?*

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■ We avoid many problems with time synchronization because our simulations run in real-time -- hence we can use the real-time mode of ACT-R

■ Running on separate machines avoids conflict of resources that would lead to timing issues

- ◆ No degradation of resources due to simulation -- makes it easier for ACT-R to keep up with a dynamic simulation in real-time
- ◆ Prevents ACT-R from locking out other processes