

Strategy Shift in Prisoner's Dilemma through Utility Learning

Kwangsue Cho

Christian Schunn

Learning Research and Development Center

Univ. of Pittsburgh

Prisoner's Dilemma (PD)

- ✍ Non zero-sum game
- ✍ Goal: Getting big payoffs
- ✍ Two players are involved.
- ✍ Strategy Choice without knowing each other's choice
 - ✍ In each trial, each player must choose between the *cooperate* (C) and the *defect* (D) strategy
- ✍ Players receive payoffs depending on both of the moves
 - ✍ Your payoffs depend on your partner's move
- ✍ In a typical study two players participate in multiple trial play of the game.

Prisoner's Dilemma Payoff Matrix

		Player 2	
		Defect2	Cooperate2
Player 1	Defect1	-1 -1	+10 -10
	Cooperate1	-10 +10	+1 +1

- ✍ Expected Payoff
 - ✍ Defect = $(-1 + 10) / 2 = 4.5$
 - ✍ Cooperate = - 4.5
 - ✍ Rational action = Defect
 - ✍ Irrational action = Cooperate
- ✍ A conflict between rational and irrational behavior
 - ✍ The loss from defect vs. the benefits from Coop.
- ✍ Strategy Shift = learning process
 - ✍ from the *Defect* to the *Cooperate*

Motivation & Goal

✎ Game theory assumes *Rationality*

- ✎ Chaotic performance in the beginning is ignored.
- ✎ Equilibrium state in games needs multi-hundreds of trials
- ✎ Human cognition (learning and adaptation) is ignored
- ✎ Lack of short-term prediction

✎ Simulation of Strategy shift in the PD

- ✎ To consider human learning or adaptation process

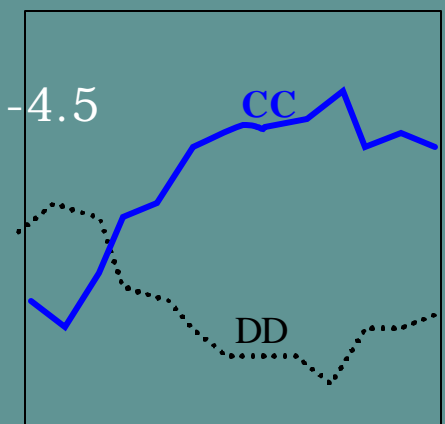
Strategy Shift Phenomena

✎ Strategy Shift

- ✎ From rational choice in the beginning to irrational choice later on
- ✎ From Defect To Cooperate

✎ Conflicts between immediate payoff and goal

- ✎ Immediate payoffs interfere with goal
 - ✎ Expected gain: Defect = 4.5 vs. Cooperate = -4.5



Trials

Lebiere, Wallach, & West (2000)

✍ Memory-based model

- ✍ The most likely outcomes are determined by retrieving the most active of the possible move combinations
- ✍ Retrieve most likely (most active) consequence of Cooperation and of Defection
- ✍ Pick strategy with highest gain

✍ Winner takes all

- ✍ Once a pattern of behavior is established, it seems not changeable
 - ✍ Strategy that's more common in the beginning tended to be stable
 - ✍ Self-reinforcing chunk strength
- ✍ Inherent bias for defecting in the beginning
- ✍ Strategy shift was hard to simulate

Our Model Flow

Retrieve Payoff Matrix

Calculate Expected Payoff (EP) per each strategy

Decide Strategy Choice Preference

If $EP(D) > EP(C)$ or
If $EP(D) < EP(C)$

If $EP(D) > EP(C)$

Make a Move

If $EP(D) < EP(C)$

D_Move_Defect

D_Move-Cooperate

C_Move-Defect

C_Move-Cooperate

Get Partner's Move

Receive Real Payoff (RP)

Compare RP with EP

Punish the rational choice if it fails (when $RP < EP$)
Reinforce the irrational one if it succeeds (when $RP > EP$)

Request New Goal

Utility Learning of the Model

✍ Production for rational choice is weighted in the beginning

✍ When $EP(D) > EP(C)$,

✍ (spp D_Move-Defect :failures 0 :successes 20 :efforts 100)

✍ (spp D_Move-Cooperate :failures 20 :successes 20 :efforts 100)

✍ When $EP(D) < EP(C)$,

✍ (spp C_Move-Defect :failures 20 :successes 20 :efforts 100)

✍ (spp C_Move-Cooperate :failures 0 :successes 20 :efforts 100)

Surprise-Based Utility Learning

✍ Unbalanced Reinforcement of Strategy

- ✍ Punish the rational choice if fails when $RP < EP$
 - ✍ e.g (spp Eval-Payoff-Poor-D :failure t)
- ✍ Reinforce the irrational choice if succeeds when $RP > EP$
 - ✍ E.g. (spp Eval-Payoff-Good-C :success t)

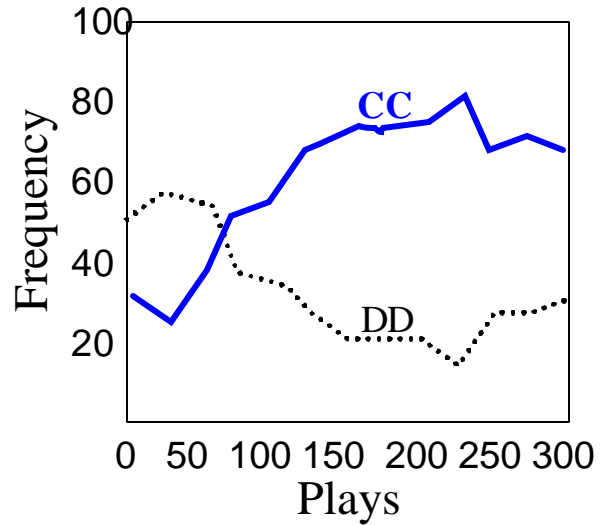
Result 1. General Fit

	DD	DC	CD	CC	r	Mean-Dev.
Human Data	30	7	8	55		
Lebiere et al	32	8	6	54	.99	.02
Our Model	20	13	12	55	.95	.06

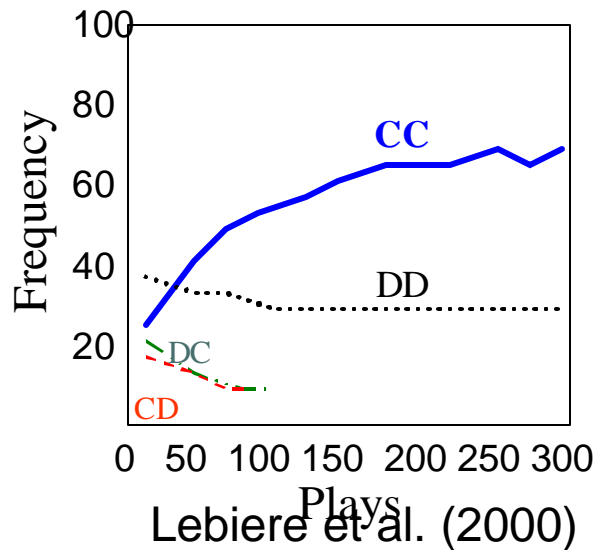
✍ Method

- ✍ 10 groups of two players
- ✍ 300 trials per group

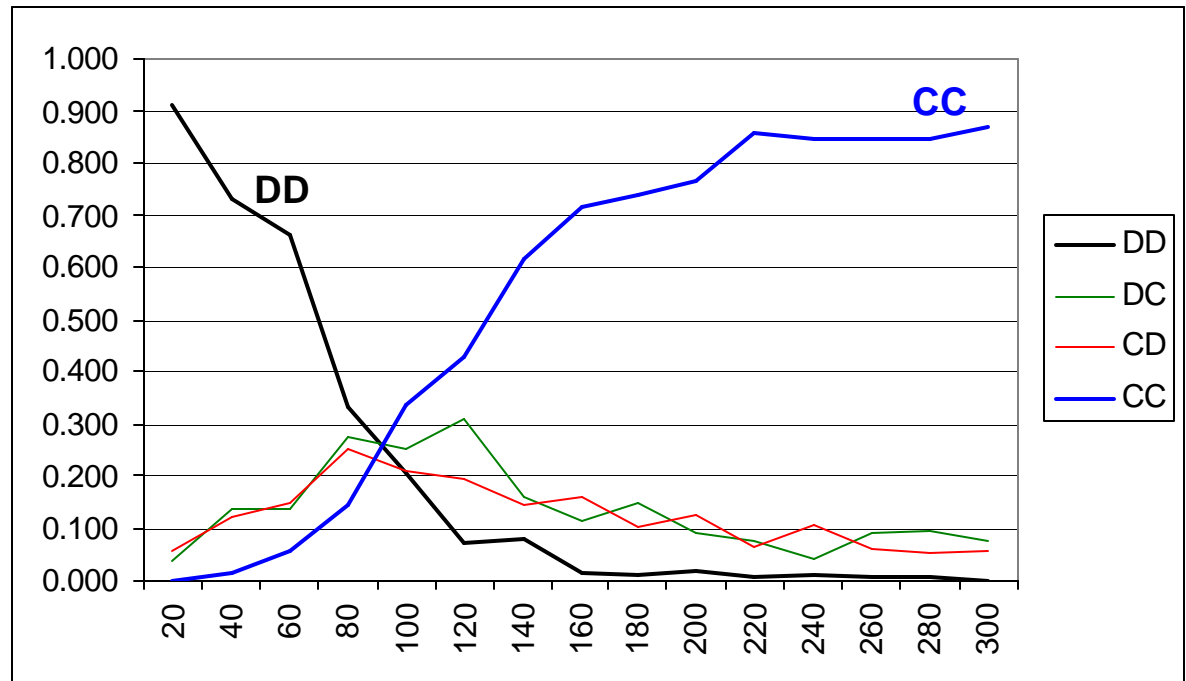
Result 2. Strategy Shift



Rappoport et al. (1976)



Lebiere et al. (2000)



Result 3. Individual difference

Human Data

Run	DD	DC	CD	CC
1	1	1	1	97
2	7	1	1	92
3	14	1	2	83
4	4	5	5	86
5	21	4	3	72
6	24	5	5	66
7	54	12	7	27
8	34	2	52	11
9	58	25	5	12
10	83	9	4	3
	30	7	8	55

Cho & Schunn

Run	DD	DC	CD	CC
1	20	4	8	68
2	23	7	6	64
3	9	9	19	63
4	20	9	12	59
5	20	14	10	56
6	21	17	7	55
7	20	18	8	54
8	16	16	18	50
9	32	11	17	40
10	22	23	15	40
	20	13	12	55

Lebiere et al.

Run	DD	DC	CD	CC
1	1	0	2	97
2	1	1	2	96
3	2	9	2	87
4	5	4	10	81
5	4	19	12	65
6	10	13	12	65
7	13	21	18	48
8	92	4	3	1
9	93	3	3	1
10	95	3	2	0
	32	8	6	54

Conclusion

- ✍ Our model captures features not previously captured
 - ✍ model captures both the asymptotic behavior and the strategy shift
- ✍ The model doesn't assume any altruistic assumption
 - ✍ considering partner's gains as general solutions in the Game theory. Instead, the model seeks moves for its own maximal gain.
- ✍ Surprise based learning
 - ✍ Unbalanced or weighted reinforcement learning
 - ✍ Reinforcing each strategy as either good or poor
 - ✍ the natural defecting strategy is reinforced negatively when it fails, but not positively even when it succeeds.
 - ✍ the cooperative is reinforced only positively when it's successful

Limitations and Difficulties

- ✍ Dominant preference for defecting in the beginning
- ✍ Sometimes human players start with the irrational choice, cooperation
 - ✍ We don't model it
- ✍ Learning too slow
 - ✍ Utility learning unit is limited to 1 in/decrement per experience
- ✍ Turning off surprise-based learning
 - ✍ Habituation process?
 - ✍ Once a behavior is set, it doesn't need to be strengthened or weakened

Acknowledgement

Christian Lebiere

Dan Bothell

Raluca Budiu

John Anderson

Especially

You, ACT-R fellows