

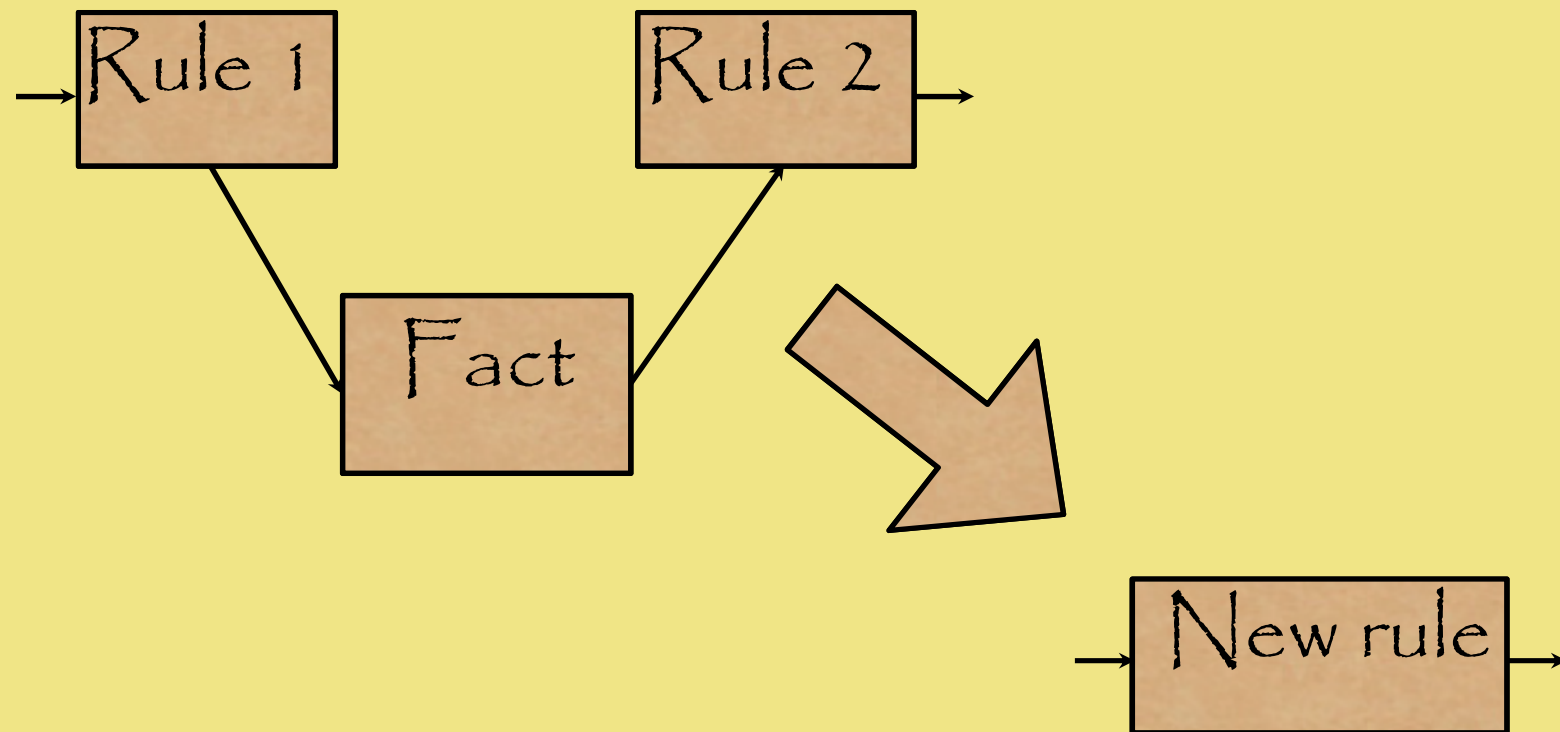


# Learning new production rules

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# Combination and Specialization



Production compilation:



## specialization and combination

- Production rules are specialized by factoring out the retrieval request and retrieval match (if any, otherwise there is no specialization)
- Production rules are combined by merging two rules into one



# Support for skill acquisition

- By factoring out retrievals
  - Speedup because retrievals are no longer needed
  - It reduces errors (retrieval errors)
  - Frees up “working memory” by reducing interference



# Discontinuous learning

- In declarative memory, activation (how often is a chunk used) determines its success
- In procedural memory, utility (how efficient is the use of knowledge) determines its success
- A shift from declarative to procedural may produce transition effects: for example, U-shaped learning



# Example: Addition

```
(P initialize-  
  addition  
=goal>  
  ISA      add  
  arg1     =num1  
  arg2     =num2  
  sum      nil  
==>  
=goal>  
  sum      =num1  
  count    zero  
+retrieval>  
  ISA      order  
  first    =num1)
```

```
orderx  
isa order  
first six  
second seven
```

```
(P increment-sum  
=goal>  
  ISA      add  
  sum      =sum  
  count    =count  
=retrieval>  
  ISA      order  
  first    =sum  
  second   =newsum  
==>  
=goal>  
  sum      =newsum  
+retrieval>  
  ISA      order  
  first    =count)
```



# Example: Addition

```
(P initialize-  
  addition
```

```
=goal>
```

```
ISA    add  
arg1   six  
arg2   =num2  
sum    nil
```

```
==>
```

```
=goal>
```

```
sum    six  
count  zero
```

```
+retrieval>
```

```
ISA    order  
first  six)
```

```
orderx  
isa order  
first six  
second seven
```

```
(P increment-sum  
=goal>
```

```
ISA    add  
sum    six  
count  =count
```

```
orderx>
```

```
ISA order  
first six  
second seven
```

```
==>
```

```
=goal>
```

```
sum    seven  
+retrieval>  
ISA order  
first  =count)
```



# Example: Addition

```
(P initialize-  
  addition
```

```
=goal>
```

```
  ISA      add  
  arg1     six  
  arg2     =num2  
  sum      nil
```

```
==>
```

```
=goal>
```

```
  sum      six  
  count    zero
```

```
+retrieval>
```

```
  ISA order  
  first    six)
```

```
(P increment-sum  
=goal>
```

```
  ISA add  
  sum    six  
  count =count
```

```
orderx>
```

```
  ISA order  
  first six  
  second seven
```

```
==>
```

```
=goal>
```

```
  sum seven  
+retrieval>  
  ISA order  
  first =count)
```





# Example: Addition

```
(P initialize-  
  addition
```

```
=goal>
```

```
  ISA      add  
  arg1     six  
  arg2     =num2  
  sum      nil
```

```
==>
```

```
=goal>
```

```
  sum      six  
  count    zero
```

```
+retrieval>
```

```
  ISA order  
  first   six)
```

```
(P increment-sum  
=goal>
```

```
  ISA add  
  sum  six  
  count zero
```

```
orderx>
```

```
  ISA order  
  first six  
  second seven
```

```
==>
```

```
=goal>
```

```
  sum seven  
+retrieval>  
  ISA order  
  first zero)
```



# Example: Addition

```
(P initialize-  
  addition  
=goal>  
  ISA    add  
  arg1   six  
  arg2   =num2  
  sum    nil  
==>  
=goal>  
  sum    six  
  count  zero  
+retrieval>  
  ISA    order  
  first  six)
```

```
(P new-rule  
=goal>  
  ISA    add  
  arg1   six  
  arg2   =num2  
  sum    nil  
==>  
=goal>  
  sum    seven  
  count  zero  
+retrieval>  
  isa    order  
  first  zero)
```

```
(P increment-sum  
=goal>  
  ISA    add  
  sum    six  
  count  zero  
orderx>  
  ISA    order  
  first  six  
  second seven  
==>  
=goal>  
  sum    seven  
+retrieval>  
  ISA    order  
  first  zero)
```



# What happens to other buffers?

- As long as there are no conflicts, buffer conditions and actions are all copied into the new rule
- Conflicts:
  - First rule has an action that second rule uses as a condition
    - e.g. first rule +visual>, second rule =visual>
  - Both rules have an action on the same buffer
    - e.g. first rule +manual>, second rule also +manual>



# Example: Paired Associate

```
(p read-probe
  =goal>
    isa      goal
    state    attending
    arg1      nil
  =visual>
    isa      text
    value    =val
==>
  +retrieval>
    isa      goal
    state    associated
    arg1      =val
  =goal>
    arg1      =val
    state     testing
)

zinc-9
  isa goal
  state associated
  arg1 zinc
  arg2 "9"

(p recall
  =goal>
    isa      goal
    arg1      =val
    state     testing
  =retrieval>
    isa      goal
    arg1      =val
    arg2      =ans
  ?manual>
    state    free
==>
  +manual>
    isa      press-key
    key       =ans
  =goal>
    state     read-study-item
)
```

Diagram illustrating the flow of information between the two code blocks:

- An arrow points from the `arg1 zinc` line in the `zinc-9` block to the `arg1 =val` line in the `?manual>` block of the `(p recall` block.
- Another arrow points from the `arg2 "9"` line in the `zinc-9` block to the `arg2 =ans` line in the `?manual>` block of the `(p recall` block.



# Example: Paired Associate

```
(p read-probe
  =goal>
    isa      goal
    state    attending
    arg1     nil
  =visual>
    isa      text
    value    zinc
==>
  +retrieval>
    isa      goal
    state    associated
    arg1     zinc
  =goal>
    arg1     zinc
    state    testing
)
```

```
(p recall
  =goal>
    isa      goal
    arg1     zinc
    state    testing
  zinc-9>
    isa      goal
    arg1     zinc
    arg2     "9"
  ?manual>
    state    free
==>
  +manual>
    isa      press-key
    key      "9"
  =goal>
    state    read-study-item
)
```



# Example: Paired Associate

```
(p read-probe
  =goal>
    isa      goal
    state    attending
    arg1     nil
  =visual>
    isa      text
    value    zinc
==>
  +retrieval>
    isa      goal
    state    associated
    arg1     zinc
  =goal>
    arg1     zinc
    state    testing
)
```

```
(p recall
  =goal>
    isa      goal
    arg1     zinc
    state    testing
  zinc 9>
    isa      goal
    arg1     zinc
    arg2     "9"
  ?manual>
    state    free
====>
  +manual>
    isa      press-key
    key      "9"
  =goal>
    state    read-study-item
)
```





# Parameter Learning: what we want from it

- Gradual introduction of new rules: after the first opportunity for the rule to be learned, it should take some more practice or experience before it will regularly be used
- Evaluation of new rules
  - If the new rule is better than the parents, it should eventually fire whenever it matches
  - If the new rule is worse than the parents, it should eventually not fire anymore





# Utility of new rules

- Utility is learned according to:

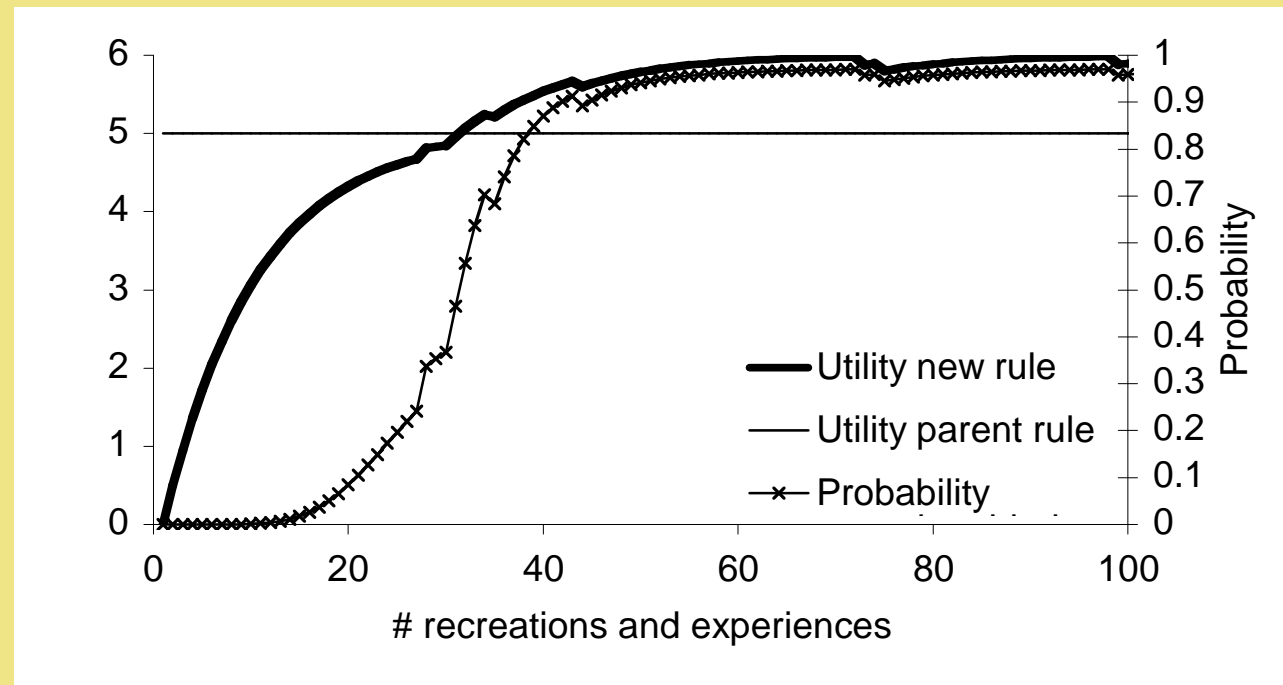
$$U_i(n) = U_i(n-1) + \alpha[R_i(n) - U_i(n-1)]$$

- A new rule initially receives a Utility of zero. Each time it is recreated, its Utility is updated:

$$U_i(n) = U_i(n-1) + \alpha[U_{parent}(n-1) - U_i(n-1)]$$



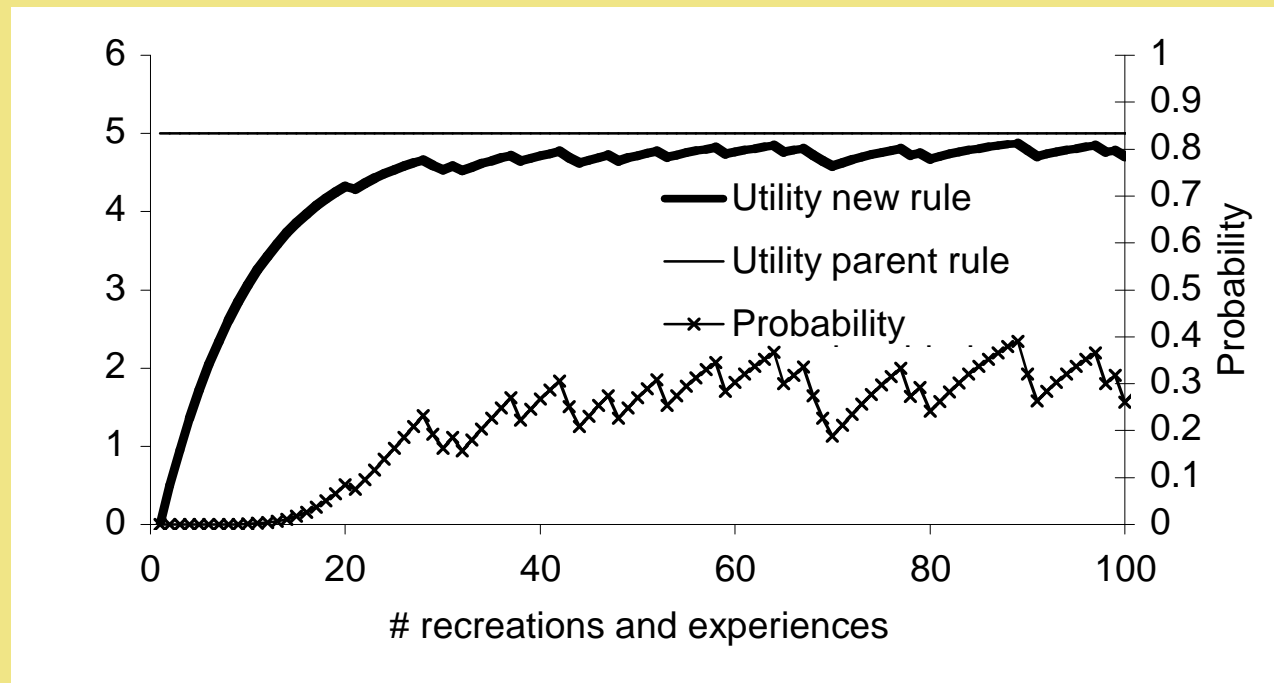
# Parameter learning: example



Noise = 0.2  $\alpha=0.1$  Utility new rule = 6



# Parameter learning: example



Noise = 0.2  $\alpha=0.1$  Utility new rule = 4



# Properties

---

- It takes a while for the new rule to be learned
- Rules that are recreated more often are learned faster



# Instructions for paired associate

- start **Read the word** stimulus-read
- stimulus-read **Retrieve associate** recalled
- recalled **Test success of recall** (response found/wait)
- response found **Type response** wait
- wait **Read feedback** new trial
- new trial **Complete task** start



# Learning from instructions

## Instructions for Paired Associate Task:

- (op1 isa operator pre start action **read** arg1 fill post stimulus-read)
- (op2 isa operator pre stimulus-read action **associate** arg1 filled arg2 fill post recalled)
- (op3 isa operator pre recalled action **test-arg2** arg1 respond arg2 wait)
- (op4 isa operator pre respond action **type** arg2 **response** post wait)
- (op5 isa operator pre wait action **read** arg2 fill post new-trial)
- (op6 isa operator pre new-trial action **complete-task** post start)



# Example productions

```
(p retrieve-operator
  =goal>
    isa task
    state =state
    step ready
==>
  +retrieval>
    isa operator
    pre =state
    =goal>
      step retrieving-
operator)
```

```
(p type-arg2
  =goal>
    isa task
    step retrieving-operator
    =imaginal>
      isa args
      arg2 =val
    =retrieval>
      isa operator
      action type
      arg2 response
      post =state
    ?manual>
      state free
==>
  +manual>
    isa press-key
    key =val
  =goal>
    state =state
    step ready)
```

(op4 isa operator task assoc pre respond action **type** arg2 **response** post wait)



# Compiled production

```
(p production323
  =goal>
    isa task
    task assoc
    state respond
    step ready
  =imaginal>
    isa args
    arg2 =val
  ?manual
    state free
==>
  +manual>
    isa press-key
    key =val
  =goal>
    state wait)
```

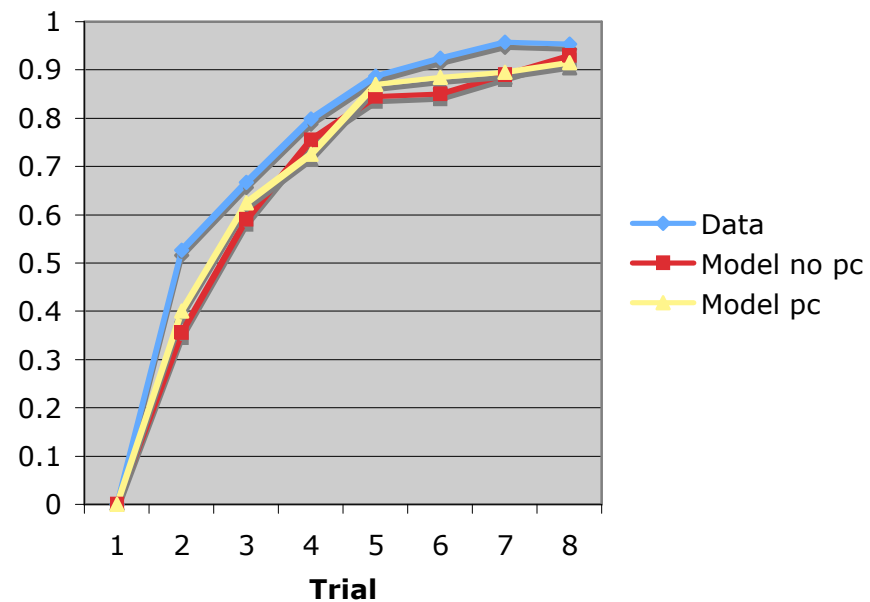
```
(op4 isa operator
  task assoc
  pre respond
  action type
  arg2 response
  post wait)
```



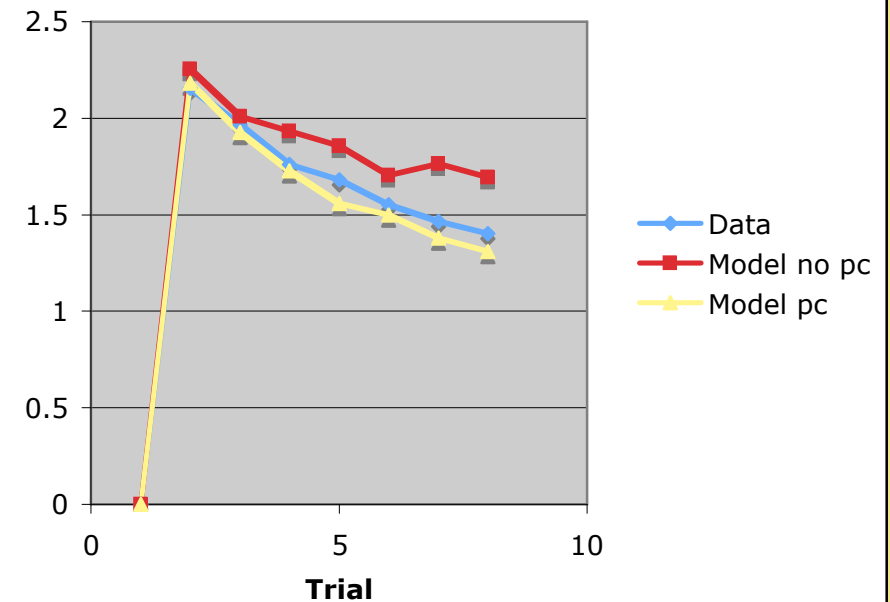


# Model results

**Accuracy**



**Latency**





# Unit Assignment: Learning the Past Tense

- Children go through three stages in learning the past tense
  - Stage 1: If they inflect an irregular verb, they do it correctly, e.g., break-broke
  - Stage 2: Children occasionally overgeneralize, e.g., break-broke
  - Stage 3: Children do it correct again: break-broke
- This is called U-shaped learning
  - Important aspect: children do not get feedback on whether or not the past tense they produce is correct.



# Learning the past tense

- This is a different model than you have seen up to now:
  - It is not an experiment (but real life!)
  - It's on a different time scale (months instead of hours)
  - It doesn't use the perceptual and motor components of ACT-R



# What is already there

The model code

generate a goal like

```
goal1  
  isa goal  
  state nil
```

And put a present tense in  
the imaginal buffer like:

```
verb23  
  isa past-tense  
  verb have  
  stem nil  
  suffix nil
```

- ❑ Your model has to fill in the stem and suffix slots in the imaginal buffer (in this case *had* and *blank*, respectively), and set the state slot in the goal to *done*.
- ❑ Three rules that are already provided in the model will then “pronounce” the word.
- ❑ The feedback the model uses is not failure or success, as kids also do not get feedback, but the costs of producing the past tense.



# Three Evaluation Productions

## Reward 5

=goal>  
isa goal  
state done  
=imaginal>  
isa past-tense  
verb =word  
suffix blank  
==>  
=goal> state nil

## Reward 4.2

=goal>  
isa goal  
state done  
=imaginal>  
isa past-tense  
verb =stem  
stem =stem  
suffix =suffix  
- suffix blank  
==>  
=goal> state nil

## Reward 3.9

=goal>  
isa goal  
state done  
=imaginal>  
isa past-tense  
stem nil  
suffix nil  
==>  
=goal> state nil



# What is already there

The model also assumes you perceive things in the environment (e.g., parents). So for each past tense the model creates itself, two examples are added to declarative memory:

word2323

isa past-tense

verb have

stem had

suffix blank

word4234

isa past-tense

verb use

stem use

suffix ed



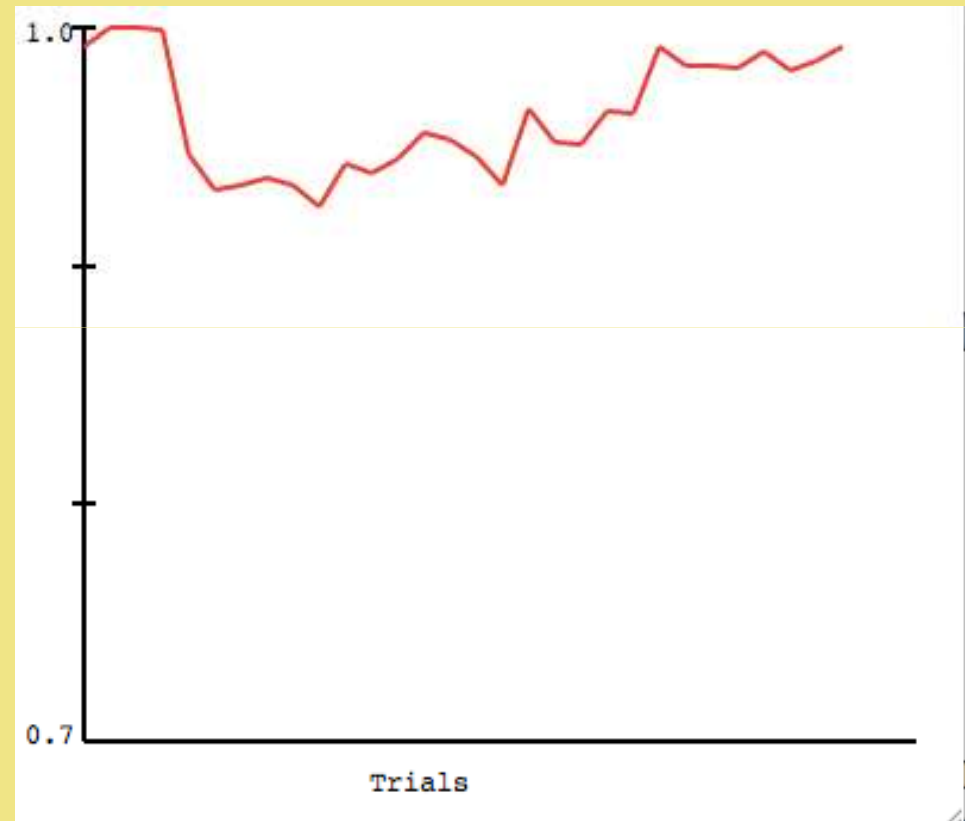
# What your model should do

- It should attempt to retrieve past tenses from memory
- Alternatively, it can try to retrieve a different past tense and do some pattern matching to apply it to the current past tense
- If something goes wrong it should just give up, and leave the stem and suffix slots empty. This represents the case where the child just used the present tense.



# What your model should learn

- Your model should learn the regular rule
- Your model should exhibit U-shaped learning







# Need 2 Retrieval Productions

```
(p retrieve1
....
==>
+retrieval>
  isa past-tense
  - suffix nil
....)
```

```
(p retrieve2
....
==>
+retrieval>
  isa past-tense
  verb =word
  - suffix nil
...)
```

Challenge for the class: Why?